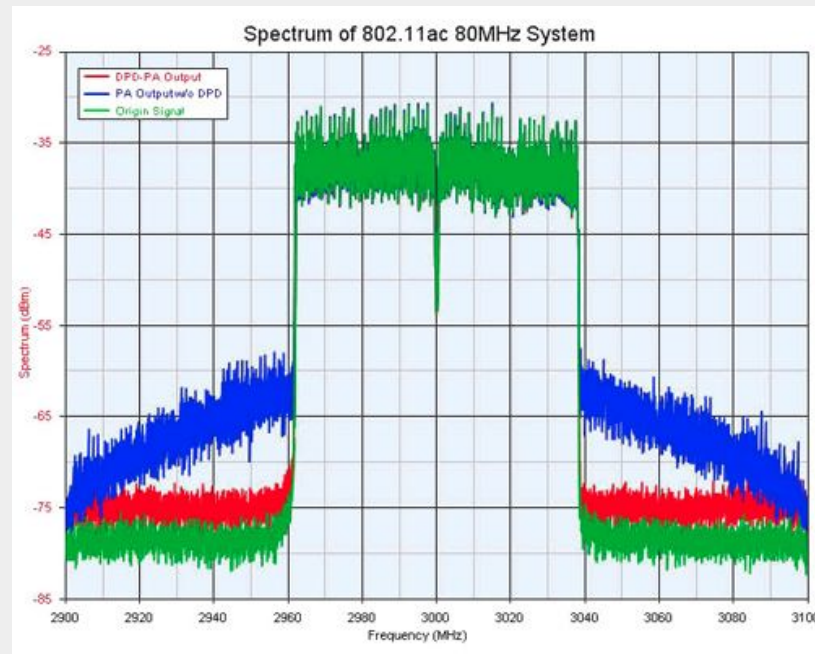


Digital Pre-Distortion

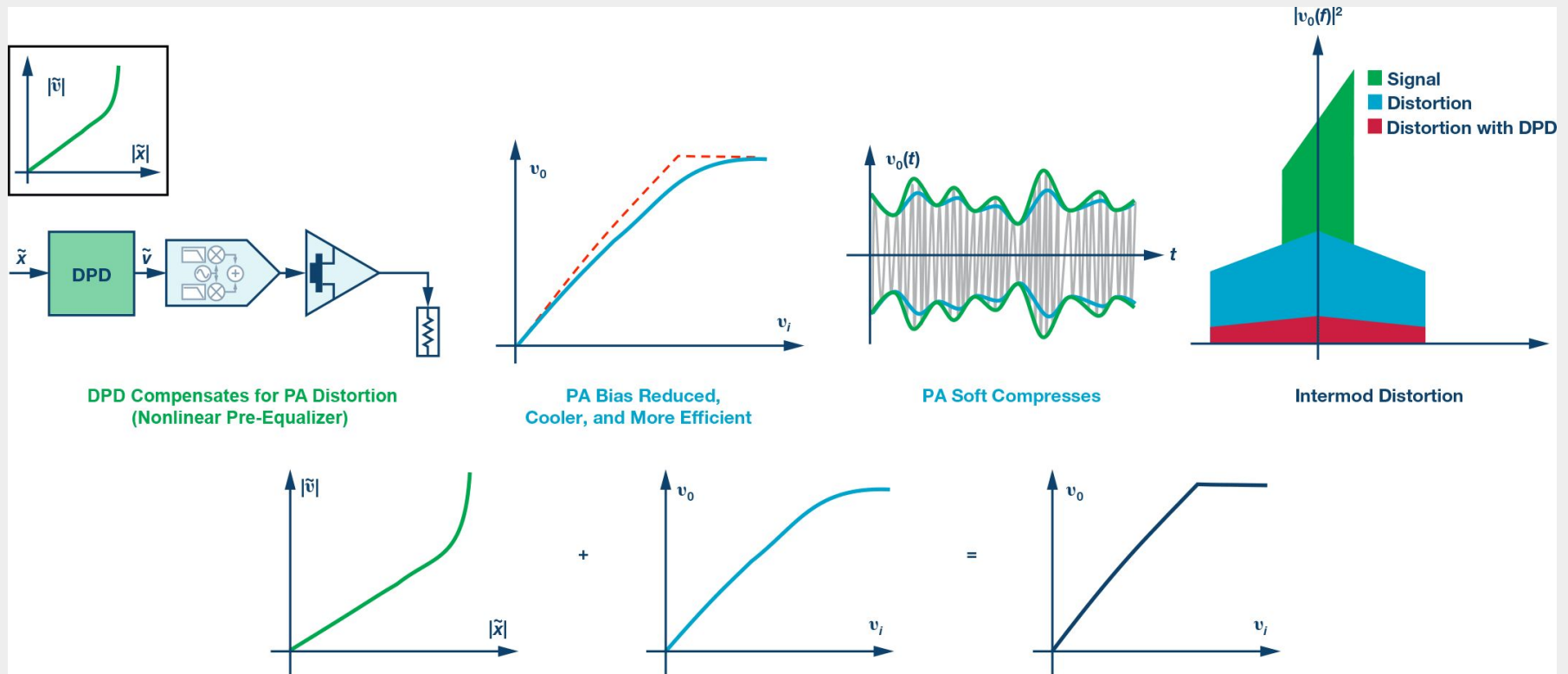
Derek Kozel

What is Digital Pre-Distortion (DPD)

- A technique for improving the linearity of power amplifiers
- Ideally the output signal of a PA is the input scaled up perfectly
- Instead the semiconductor physics causes distortions
 - Amplitude, frequency, and phase errors
- If we can predict the errors, we can try to reverse them

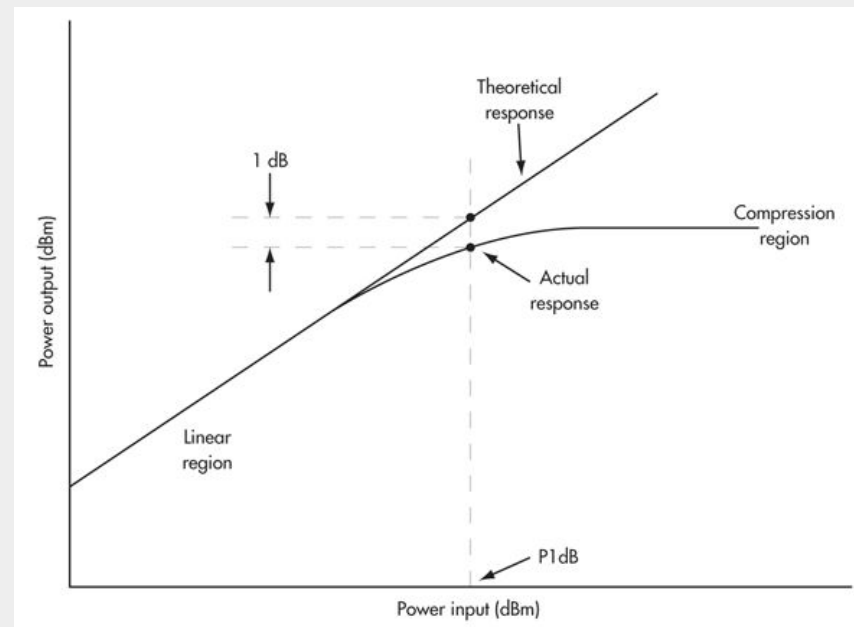


High Level Flow



Why use DPD?

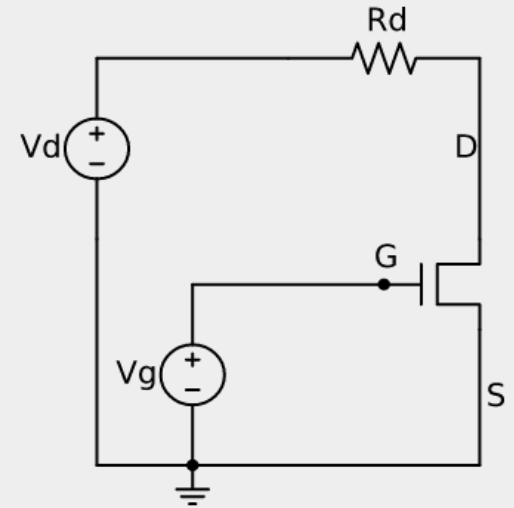
- Want to get as much power out of an amplifier as possible
 - Start getting close to limits of the device
 - Output power starts compressing
 - 1 dB increase in input -> < 1 dB increase in output
 - Output signal now a distorted version of the input!
- PA efficiency best when driven near saturation



Background Transistor Theory

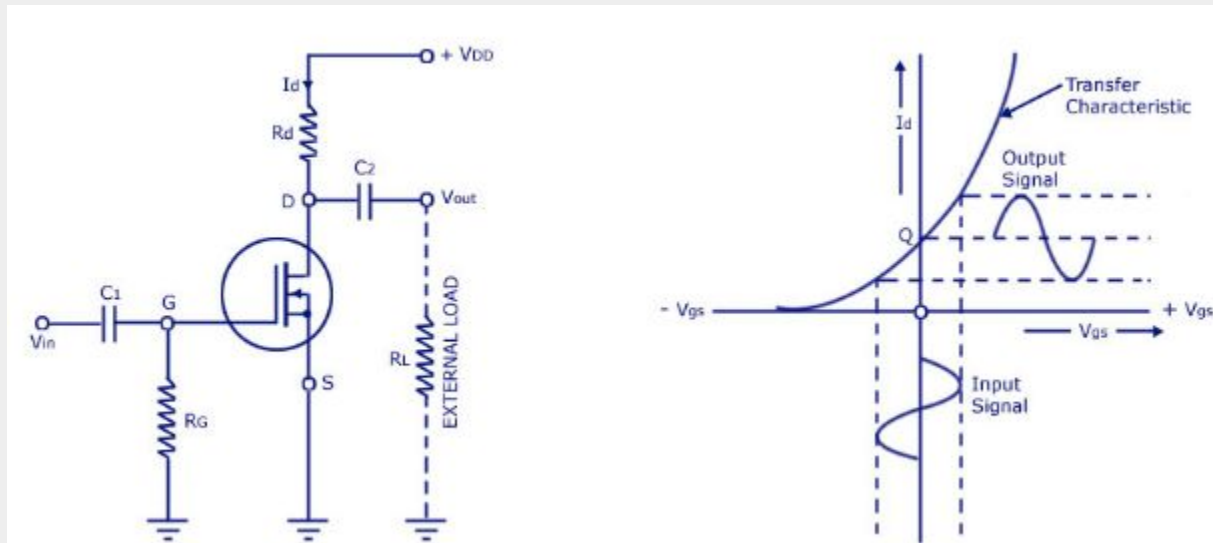
Ideal Field Effect Transistor

- Voltage controlled current source
- Three terminals (connections)
 - Gate: “control port”
 - Drain and Source: variable resistor
- Changing the voltage across these terminals changes the resistance between Drain and Source and thus the current flowing



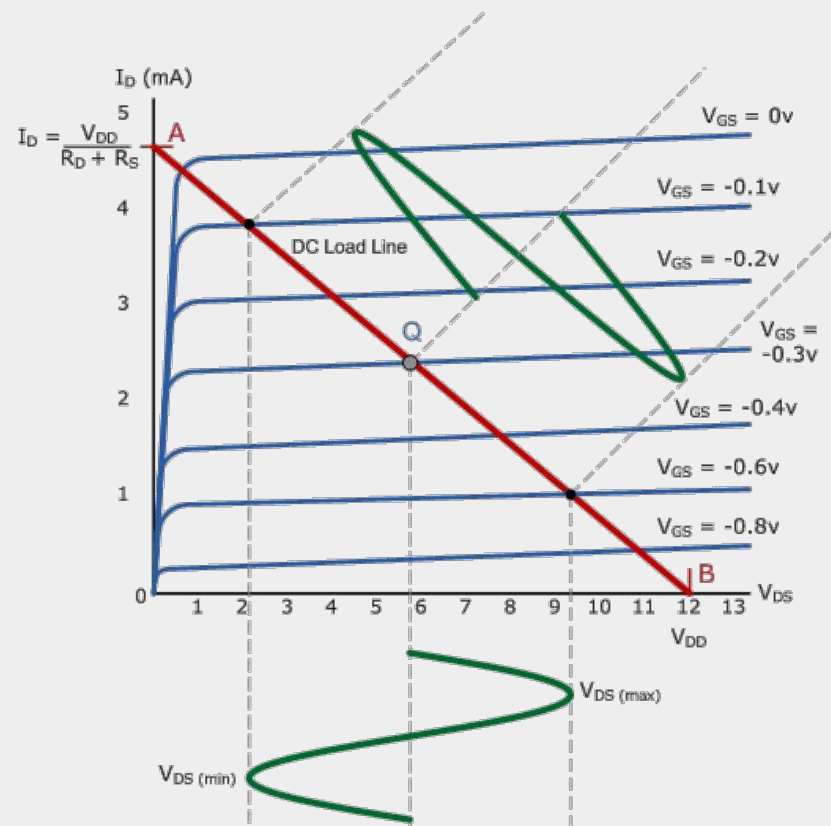
FET as an amplifier

- Usually the Gate to Source voltage is the input
- Voltage at the Drain is the output



IV Curve and Load-Line

- Shows how much does current change for a given change in Gate to Source voltage
- Load line shows the path the amplifier ideally operates on
- Looks mostly linear, but rounds off at the extremes of the load line



Distortion

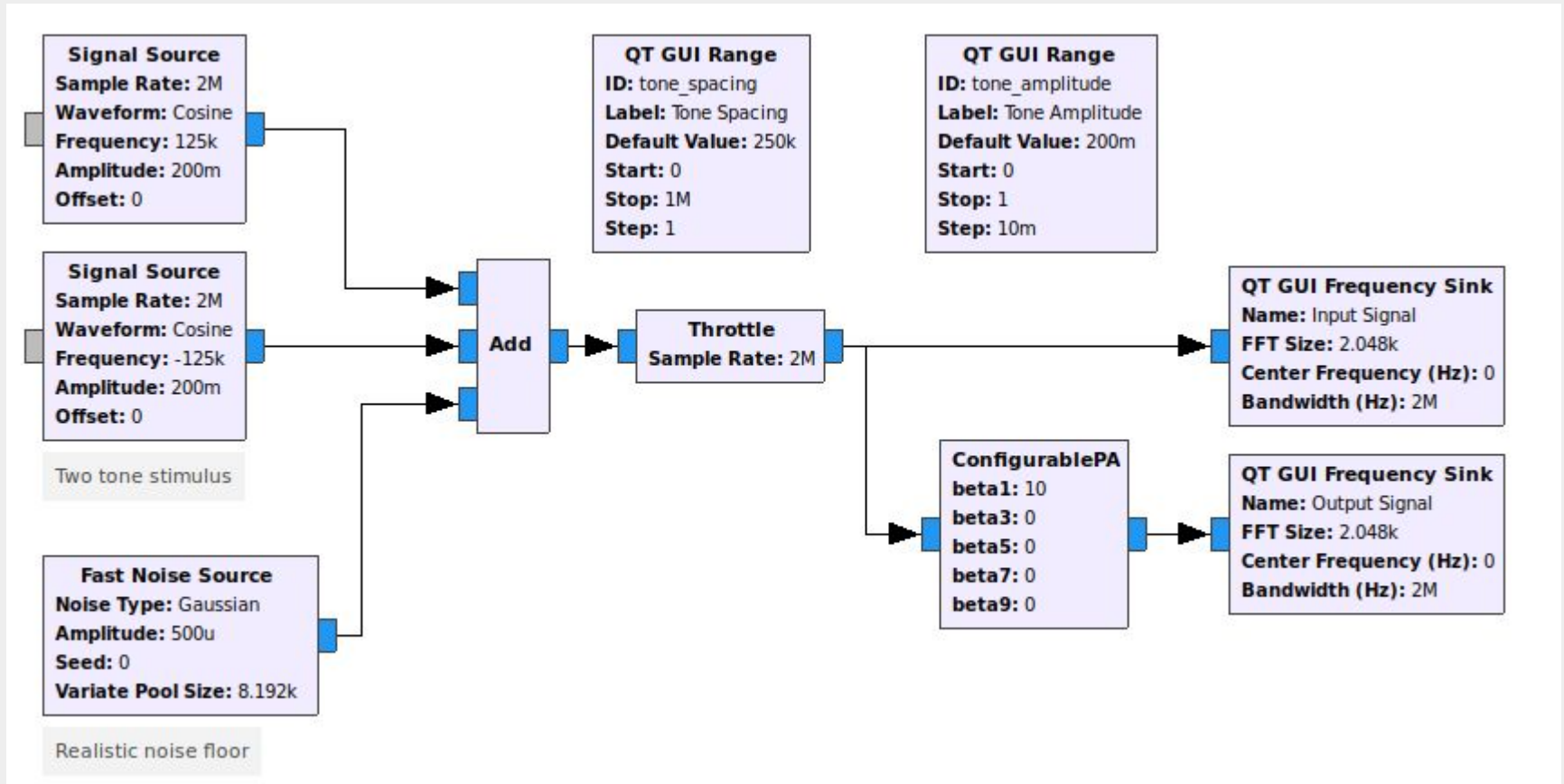
Ideal Transfer Function

- Ideally an amplifier's output voltage (across some load impedance) is:

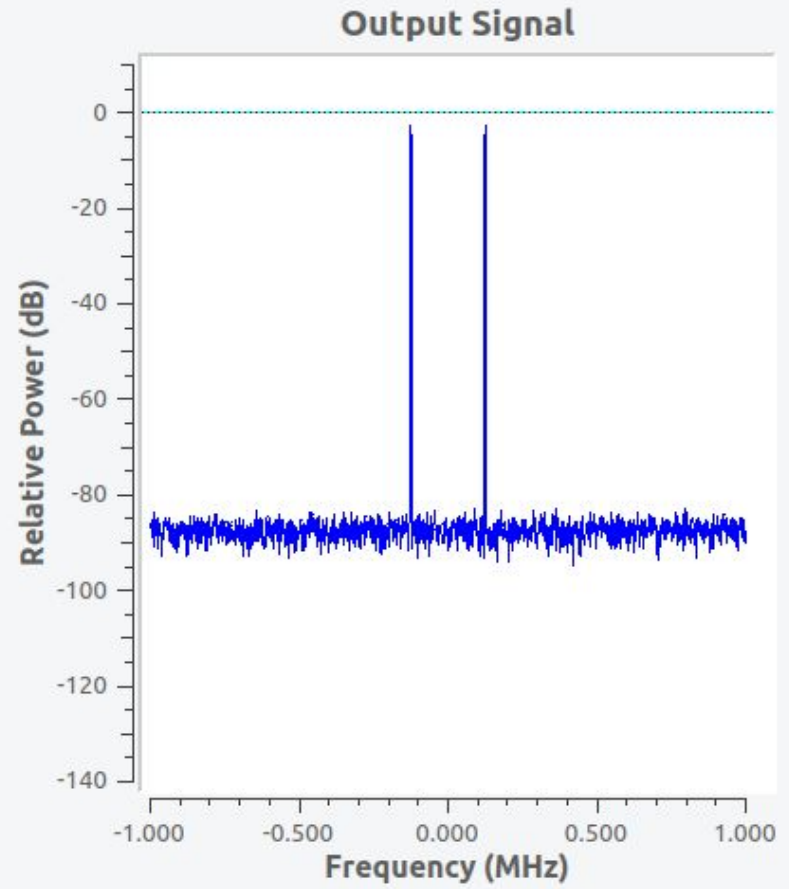
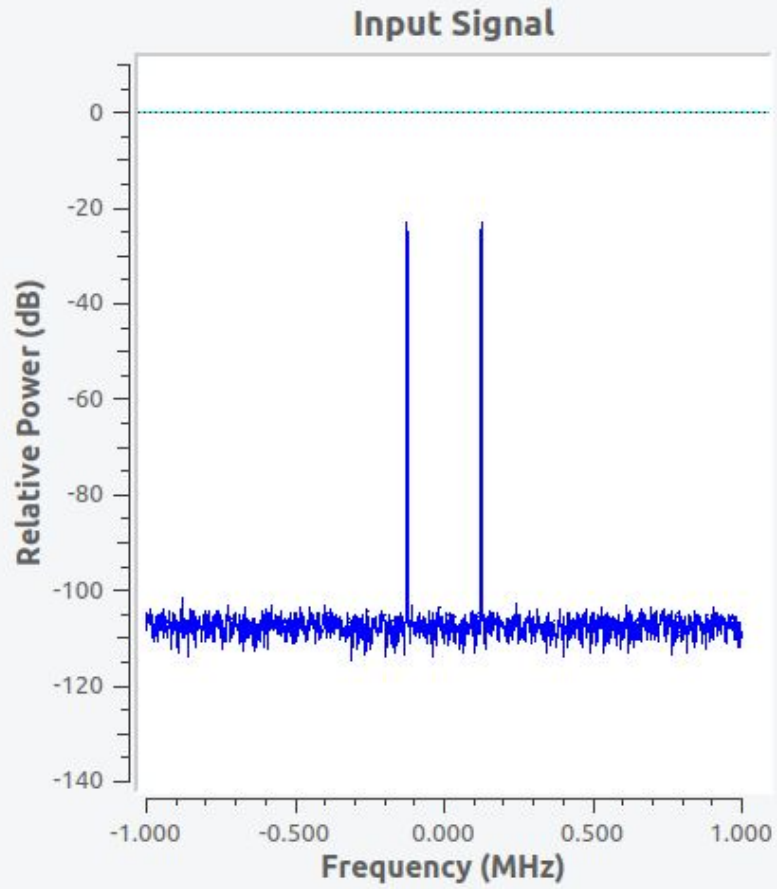
$$v_o(t) = av_i(t)$$

- Where a is the voltage gain of the amplifier

Two Tone Test Setup



Ideal Two Tone Result



Non-Linear Transfer Function

- What the output actually looks like can be modelled using a Volterra series polynomial

$$v_o(t) = a_1 v_i(t) + a_2 v_i(t)^2 + a_3 v_i(t)^3 + \dots$$

- We see the linear gain, ***a1***, and additional terms for higher order distortion
- This is only a *behavioral* model, it does not try to simulate the circuit
- Output only depends on current input value

Second Order Distortion

- The polynomial has terms for both odd and even degree terms
- Lets look at what happens when a tone is squared

$$\sin(\omega t)^2 = \frac{1}{2} (\cos(2\omega t) + 1)$$

- The result is a tone at twice the original frequency!

Third Order Distortion

- Now what about cubed?

$$\sin(\omega t)^3 = \frac{1}{4} (3 \cos(\omega t) + \cos(3\omega t))$$

- The output has energy at both the original frequency and third harmonic!
- Interesting takeaway:
 - Even order distortion does not cause tones near the fundamental
 - Odd order distortion does

Simplified Volterra Series

- Let us assume that we only care about distortion resulting in signals near our fundamental
 - Only include odd power terms

$$v_o(t) = a_1 v_i(t) + a_3 v_i(t)^3 + a_5 v_i(t)^5 + \dots$$

- For completeness, here's the 5th order expansion
 - Note that there is energy at the first, third, and fifth harmonics!

$$\sin(\omega t)^5 = \frac{1}{16} (10 \cos(\omega t) + 5 \cos(3\omega t) + \cos(5\omega t))$$

Two Tone Distortion

- Input signal:

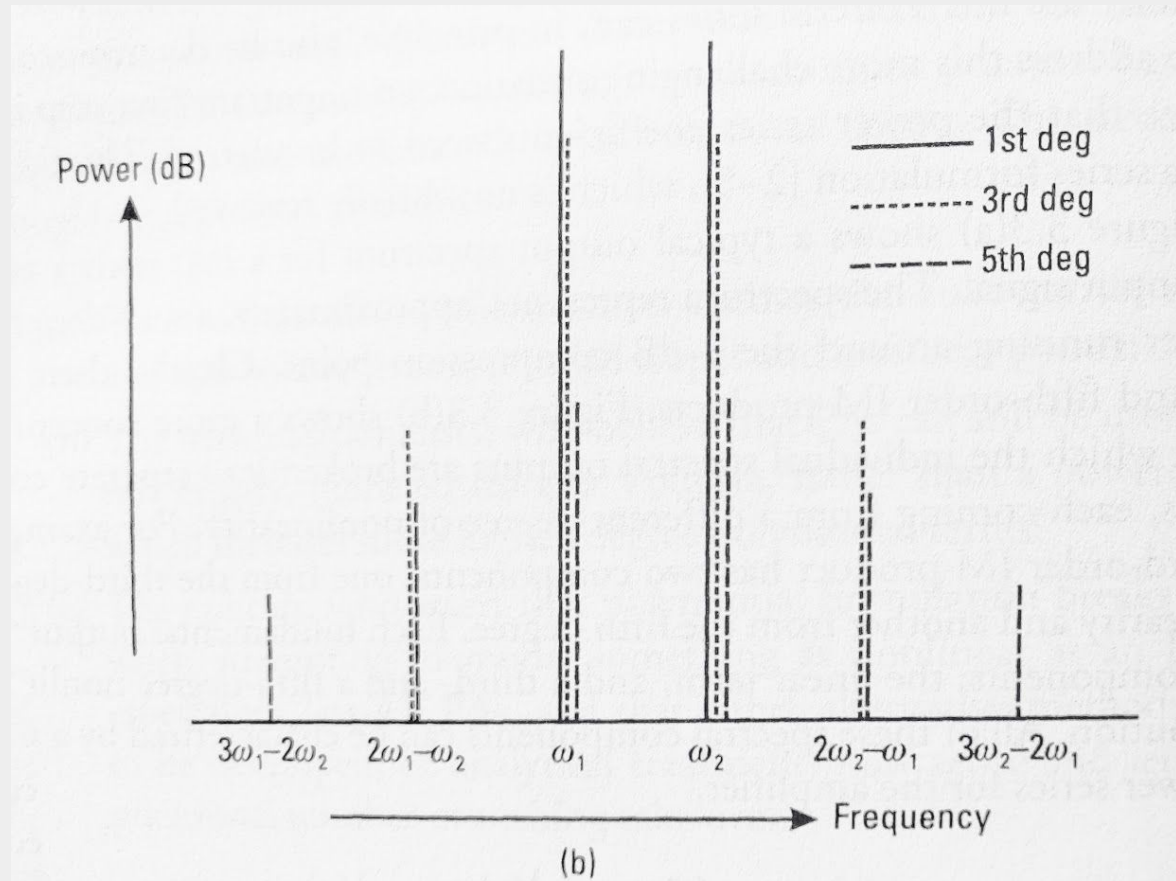
$$v_i(t) = v \cos(\omega_1 t) + v \cos(\omega_2 t)$$

- Results in In-Band distortion
 - Third order distortion will cause:

$$v_{oIM3}(t) = \left(\frac{3}{4} a_3 v^3 + \frac{25}{8} a_5 v^5 \right) \cos(2\omega_{1,2} - \omega_{2,1})$$

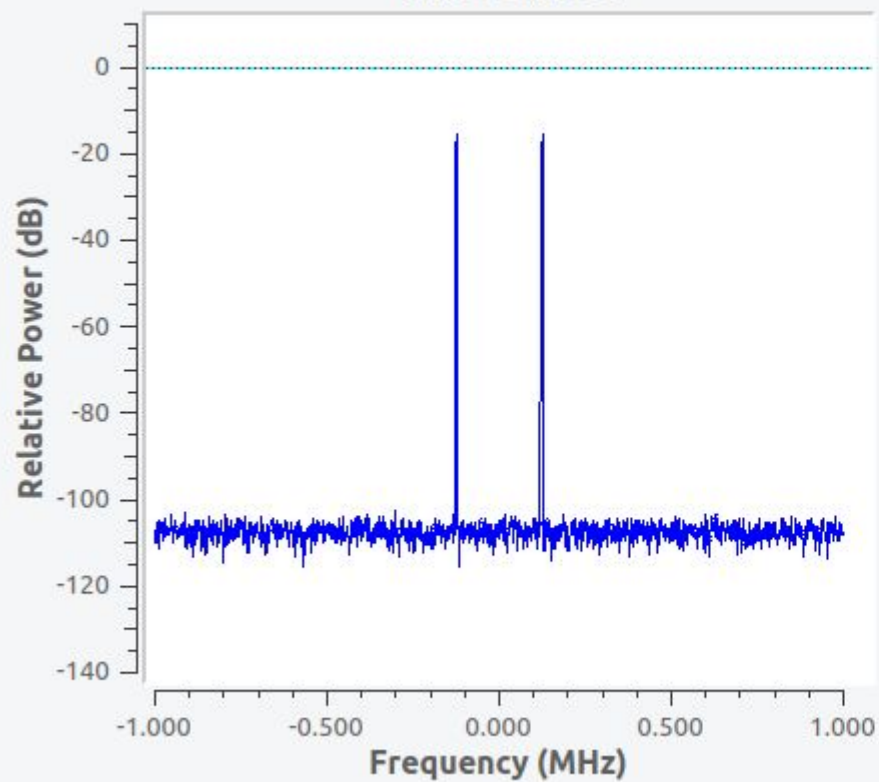
- Takeaways
 - Fundamental tone will be distorted by all odd power non-linearity
 - Sum and difference tones have energy from all higher order non-linearities

Two Tone Distortion

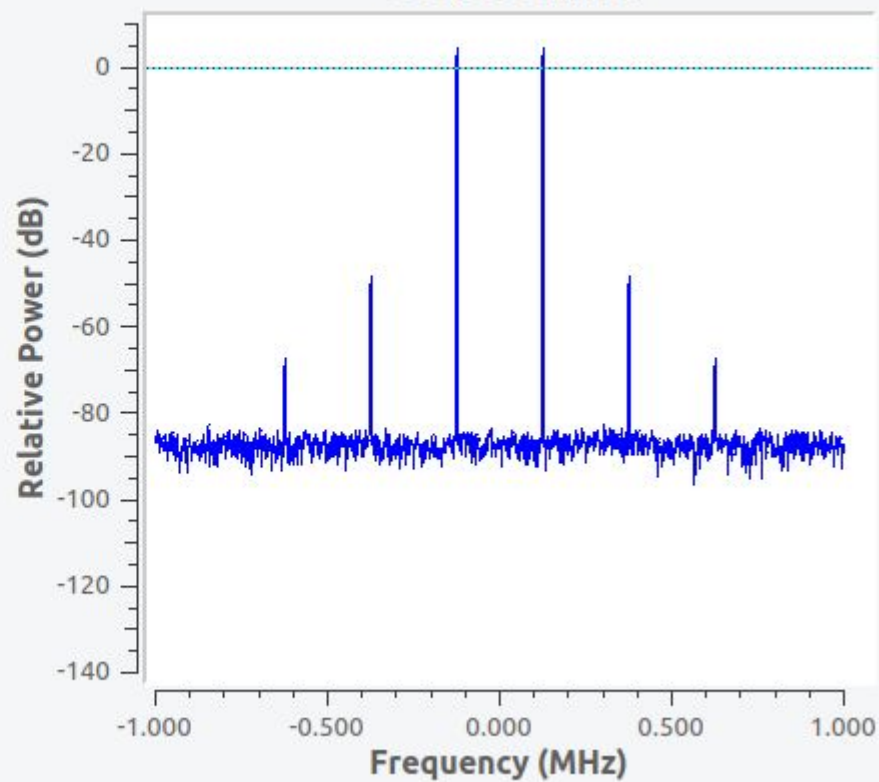


Non-Linear Two Tone Test

Input Signal

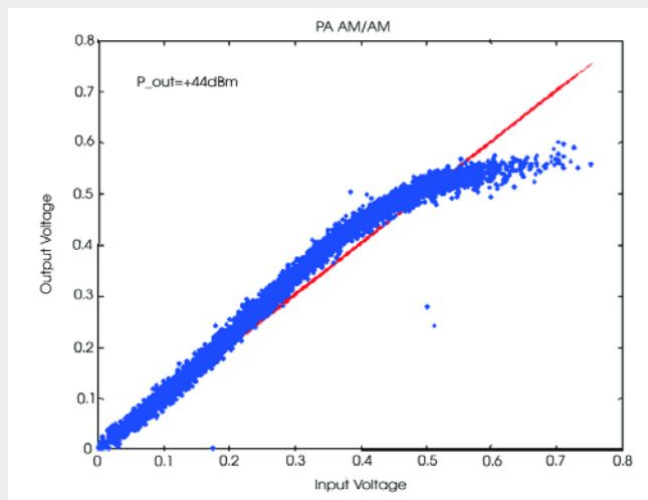


Output Signal



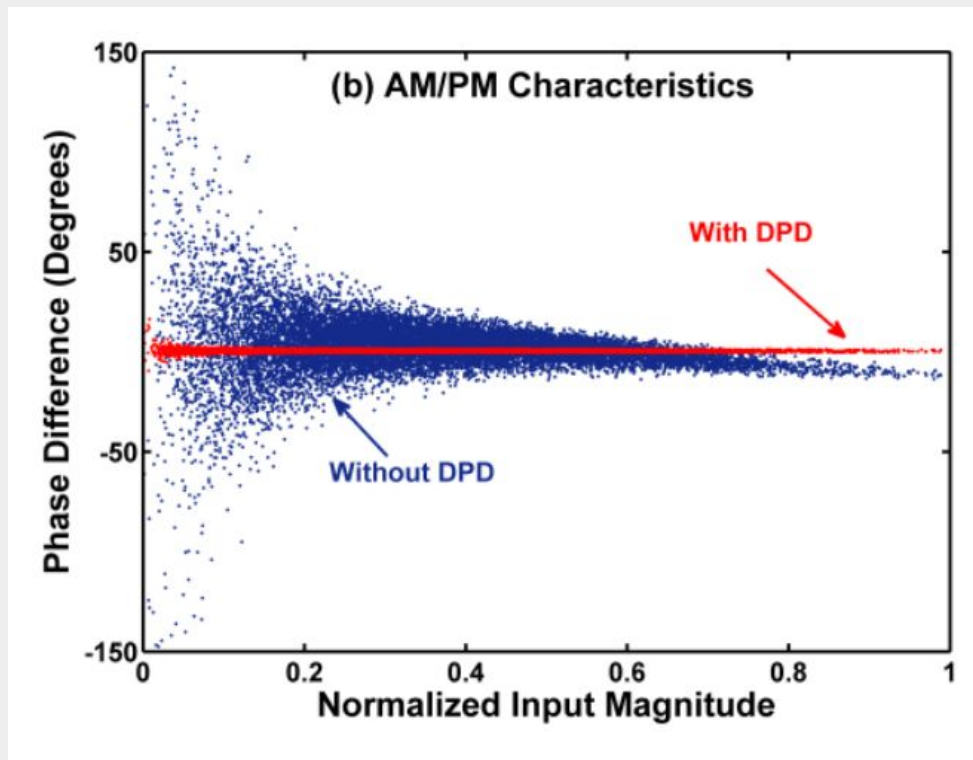
Determining Coefficients

- Now we have an equation that I assert models the behavior of a PA reasonably well
- Need to determine the a_1, a_3, a_5 coefficients for a particular PA
- Common approach:
 - Use a single tone test signal and sweep input power range
 - Measure output power (AM-AM plot)
 - Use Least Mean Squares algorithm to estimate the coefficients



... And Phase too

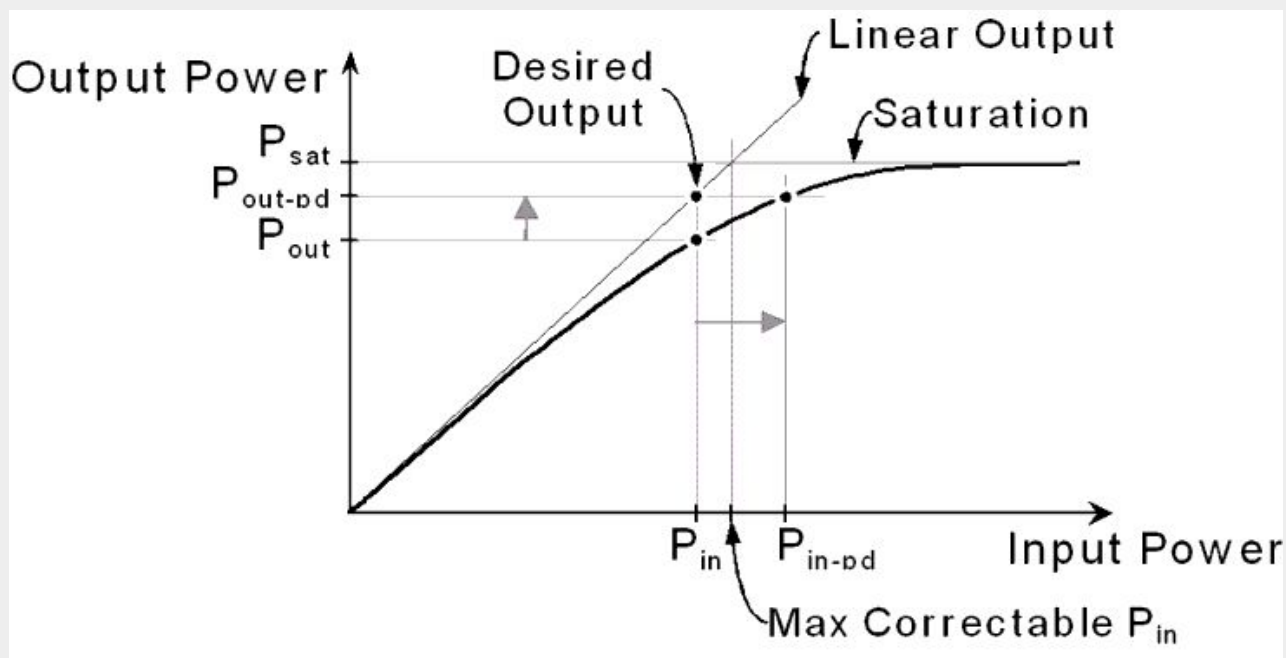
- Power amplifiers also distort phase
- The Volterra series can be expanded by making the coefficients complex



Pre-Distortion

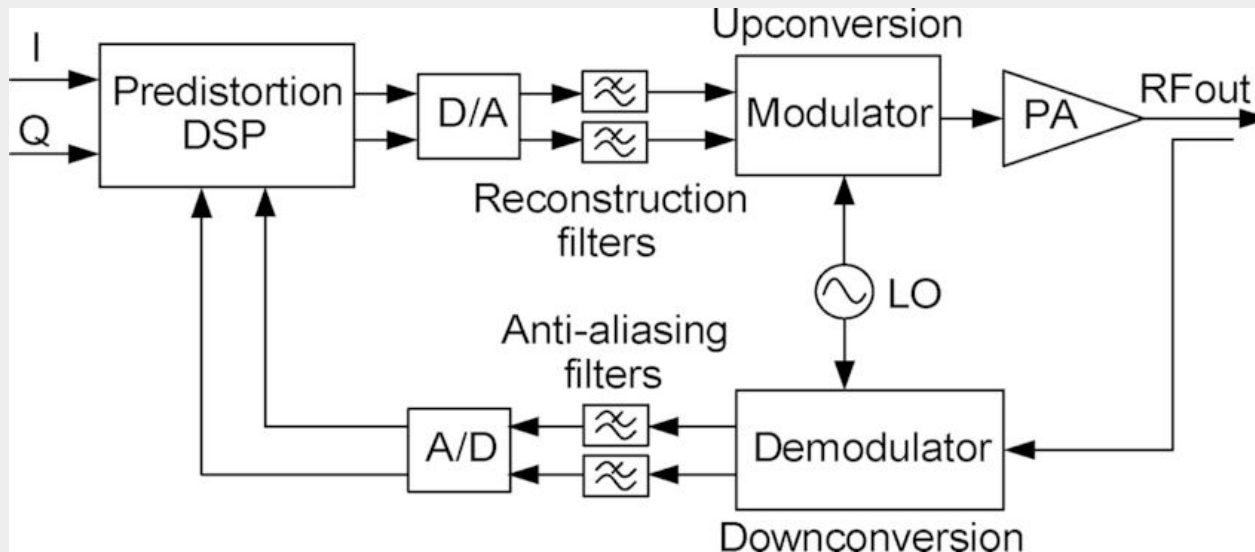
Pre-Distortion

- Need to increase the input power to account for the distortion
- Can only increase to the limit of the input driver
 - Total dynamic range decreased, but is now more linear



Inverting the Transfer Function

- Possible to do algebraically, but the equations become lengthy quickly
 - Direct Learning method
- Most frequently an optimization loop is used
 - Algorithmically vary the coefficients while measuring PA output distortion
 - Least Mean Squares, Recursive Mean Squares, others
 - Indirect Learning

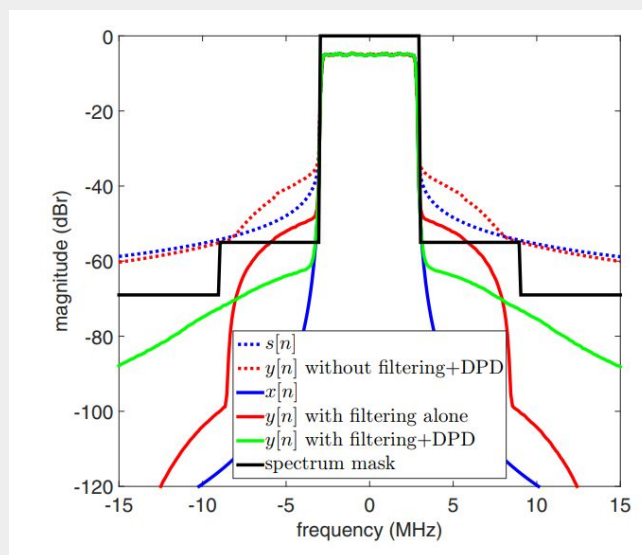


“A SiGe PA With Dual Dynamic Bias Control and Memoryless Digital Predistortion for WCDMA Handset Applications”

GNU Radio Blocks

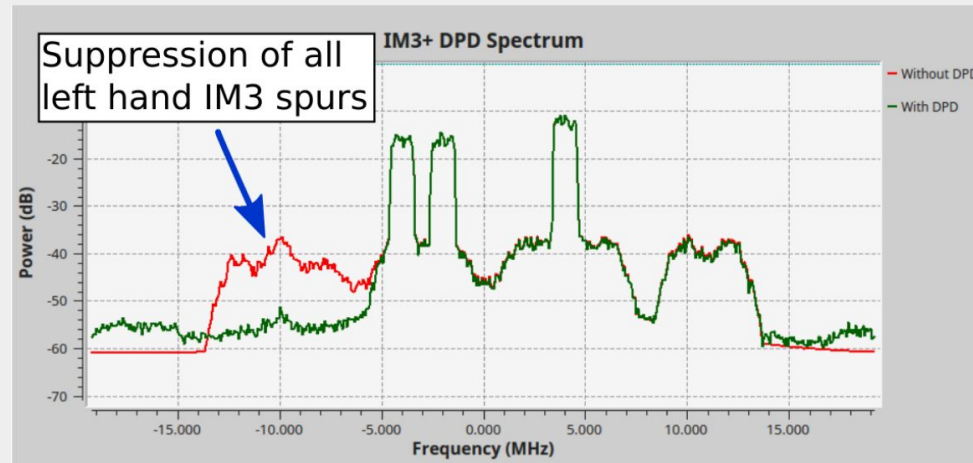
Full band DPD

- Uses Recursive Least Squares to find coefficients
- Written by Srikanth Pagadarai
 - Published in 2016 IEEE 83rd Vehicular Technology Conference
 - Srikanth Pagadarai ; Rohan Grover ; Samuel J. Macmullan ; Alexander M. Wyglinski
 - “Digital Predistortion of Power Amplifiers for Spectrally Agile Wireless Transmitters”
 - GNU Radio assistance by Travis Collins
- <https://github.com/SrikanthPagadarai/gr-dpd>
- Includes OFDM test code



Sub Band DPD

- Can isolate and compensate for a single intermodulation product
- Developed by Chance Tarver and Mahmoud Abdelaziz
 - Published in 2017 IEEE International Symposium on Circuits and Systems
 - Chance Tarver ; Mahmoud Abdelaziz ; Lauri Anttila ; Joseph R. Cavallaro
 - “Multi component carrier, sub-band DPD and GNURadio implementation”
- Uses a memoryless polynomial
- Includes the volterra series PA model used in the examples today
- Also indirect learning model



Future Plans

- Merge existing code into single OOT module
 - Authors of both existing modules supportive and able to help
- Adapt testbenches to use standard GNU Radio OFDM blocks
 - Increase flexibility, demonstrate full TX->RX impact
- Add documentation
- Add implementations of memory polynomials
 - Thermal and capacitive effects mean the output is not only dependant on the current input
- Possible Google Summer of Code project
 - Already some interested students

Thanks and Questions?

The latest version of these slides can be found at

www.derekkozel.com/talks

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