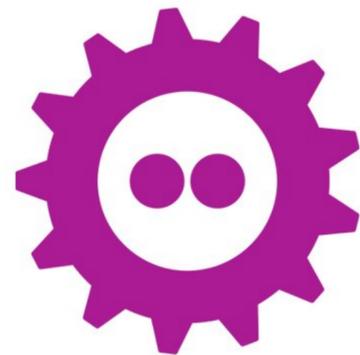


THE ROAD TO OPEN SOURCE GENERAL PURPOSE HUMANOIDS WITH DORA-RS

HAIXUAN XAVIER TAO

FOSDEM 2025 <3



FOSDEM



dora-rs



1ms.ai



pollen
robotics



Hugging Face

YOU MAY REMEMBER ME FROM FOSDEM 2024



Full Time Open Source Dev

With my own company called 1ms.ai



+



+



FOSDEM



Hugging Face

WHY DO WE NEED HUMANOIDS?

AI IS CHANGING THE WORLD.

ROBOTICS HAVE SUFFERED FOR YEARS OF LACK OF GENERALIZATION THAT AI CAN SOLVE.

**BUT, THE ONLY WAY WE CURRENTLY KNOW HOW TO MAKE "ARTIFICIAL INTELLIGENCE" IS BY
MIMICKING HUMANS**

SO WE WANT TO TEACH AI TO USE ROBOT BY MIMICKING HUMANS

THIS WOULD ENABLE THINGS LIKE HAVING ROBOT COOKING, CLEANING, FOLDING CLOTHES...

HENCE THE HUMANOID

THE TRUTH IS THAT WE DON'T KNOW HOW AI WORKS

WHAT DEFINES OPEN SOURCE GENERAL PURPOSE HUMANOIDS?

- Open Source AI
 - Model & Training Pipeline & **Maintain**
- Open Source Hardware
 - Customize & Replace & **Maintain**
- Open Source Software
 - Hack & Upgrade & **Maintain**

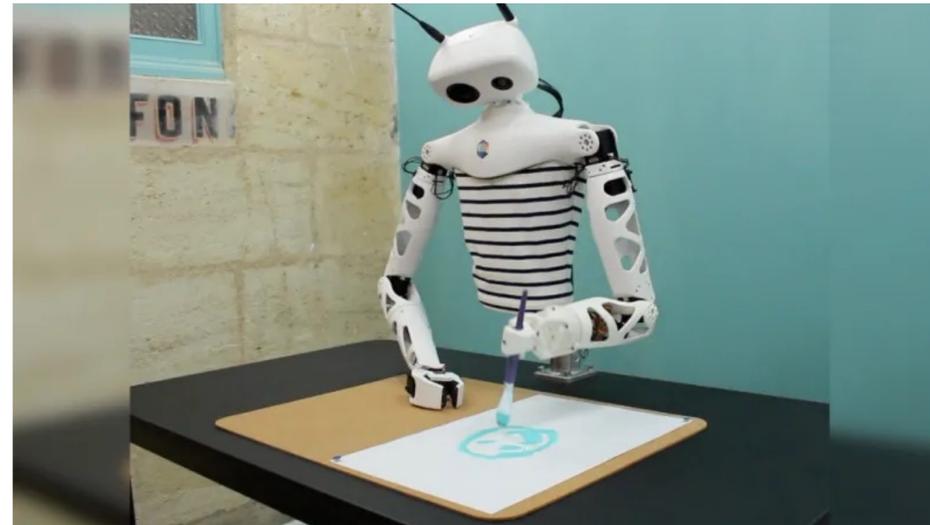


THE MANDALORIAN IS RIGHT, DON'T TRUST DROIDS!

OPEN SOURCE HUMANOIDS HARDWARE?



LeRobot - SO-ARM100



Pollen Robotics - Reachy



Zeroth Both



Trossen Robotics Mobile Aloha

THE OPEN HARDWARE HUMANOID COMMUNITY IS CURRENTLY THRIVING!

OPEN SOURCE AI MODEL IS ALSO HAVING A MOMENT!

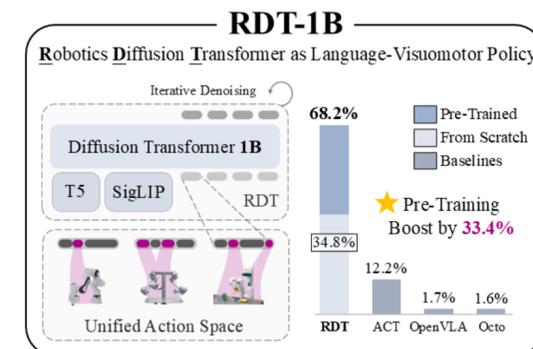


Mobile ALOHA: Learning Bimanual Mobile Manipulation with Low-Cost Whole-Body Teleoperation

Zipeng Fu¹, Tony Z. Zhao¹, Chelsea Finn¹
¹project co-leads, ¹Stanford University
<https://mobile-aloha.github.io>



Figure 1: *Mobile ALOHA*. We introduce a low-cost mobile manipulation system that is bimanual and supports whole-body teleoperation. The system costs \$32k including onboard power and compute. *Left*: A user teleoperates to obtain food from the fridge. *Right*: *Mobile ALOHA* can perform complex long-horizon tasks with imitation learning.

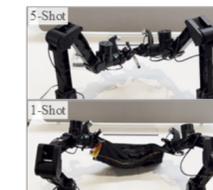


Dexterity



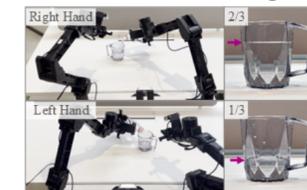
Robot walks its pet dog

Few-Shot Learning



Handover & Fold Shorts

Instruction Following

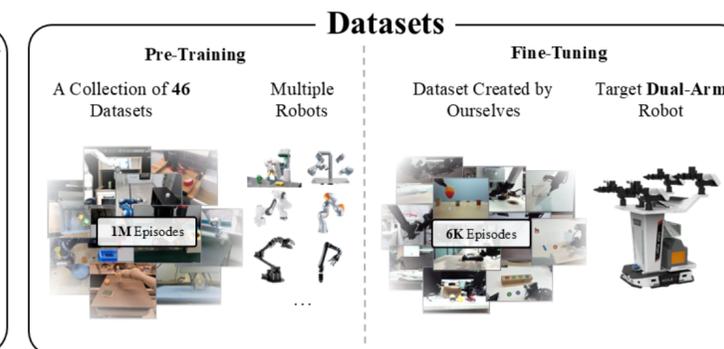


Pour water to specified level

Zero-Shot Generalizability

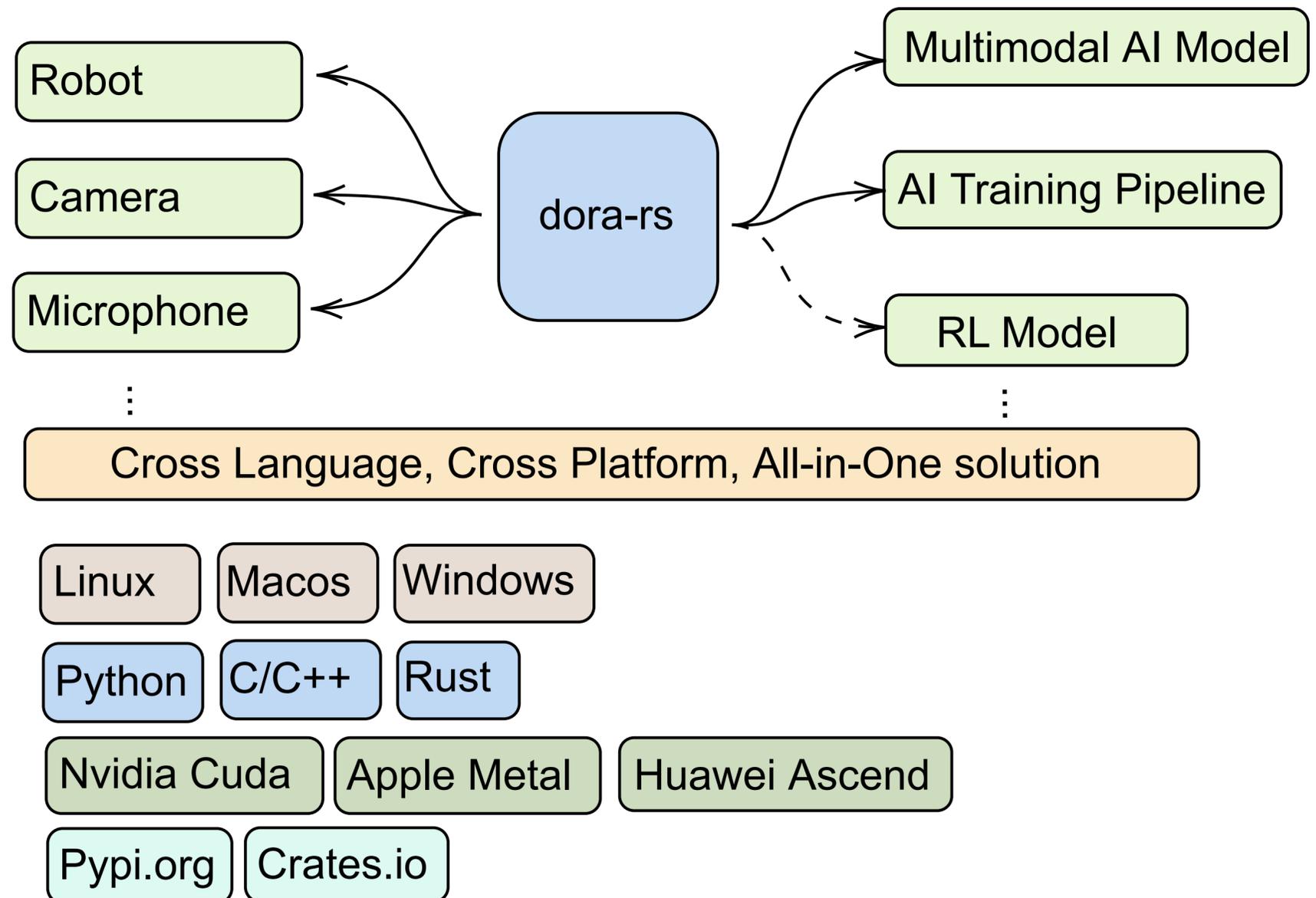


Unseen Objects & Scenes



DORA-RS IN 1 SLIDE

- dora-rs is here to bridge the gap between hardware and AI
- We believe there is key requirements of a Dataflow Oriented Robotic Architecture(DORA) to make robotic just work

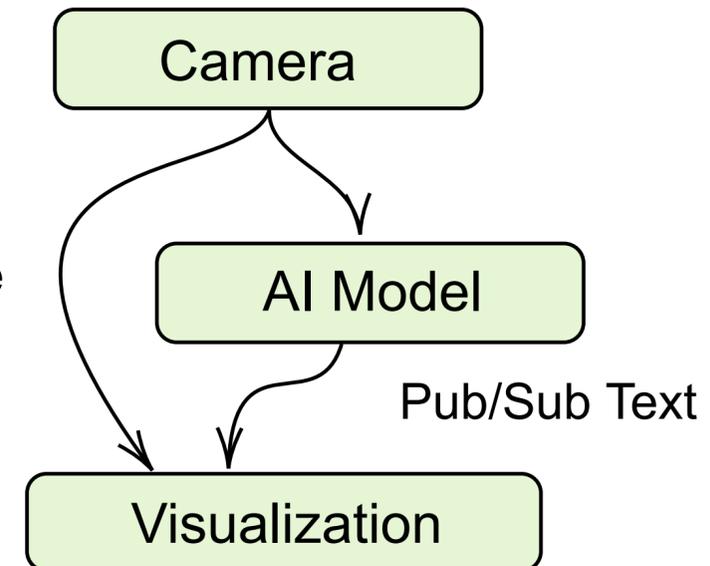


GRAPH BASED DEFINITION

```
nodes:  
- id: camera  
  build: pip install opencv-video-capture  
  path: opencv-video-capture  
  inputs:  
    tick: dora/timer/millis/50  
  outputs:  
    - image  
  
- id: dora-qwenvl  
  build: pip install dora-qwenvl  
  path: dora-qwenvl  
  inputs:  
    image: camera/image  
  outputs:  
    - text  
  env:  
    DEFAULT_QUESTION: Describe the image.  
  
- id: plot  
  build: pip install dora-rerun  
  path: dora-rerun  
  inputs:  
    image: camera/image  
    text_qwenvl: dora-qwenvl/text
```



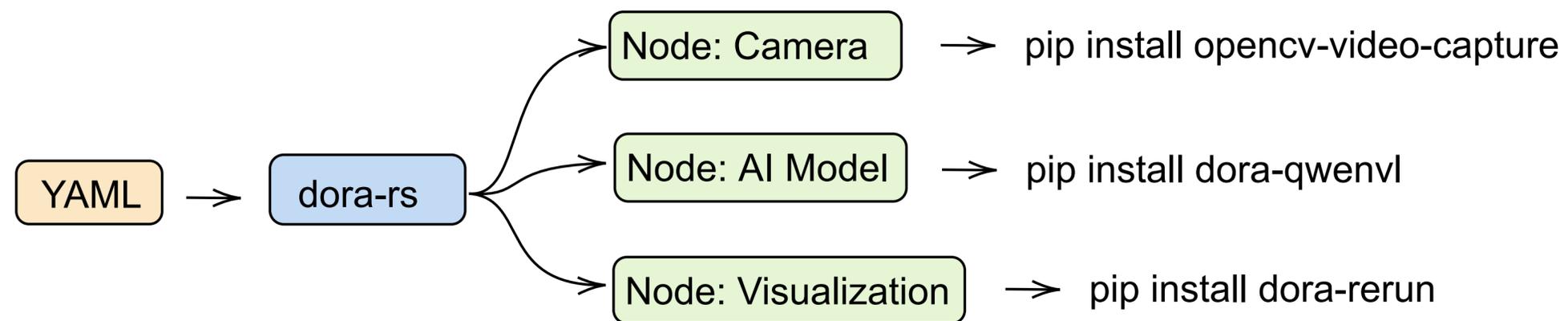
Pub/Sub Image



HOW DOES DORA DOES IT?

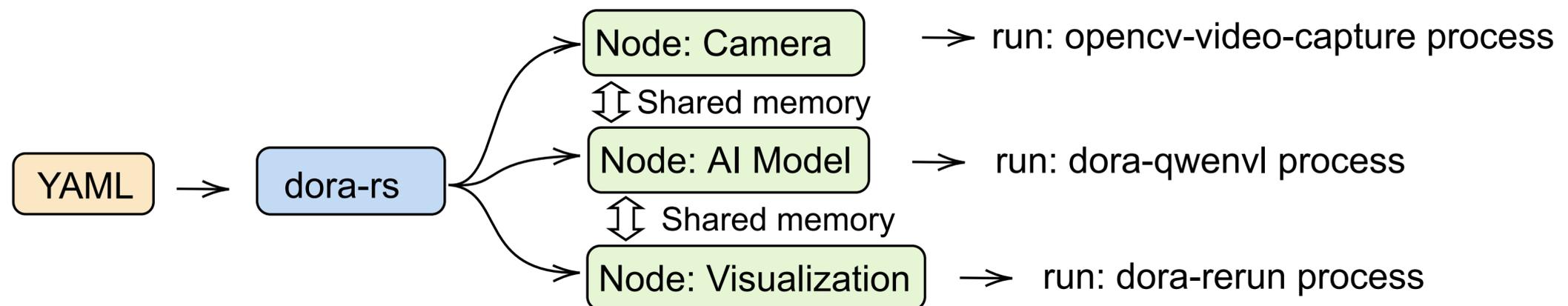
BUILD STEP

\$ dora build dataflow.yml



RUN STEP

\$ dora run dataflow.yml

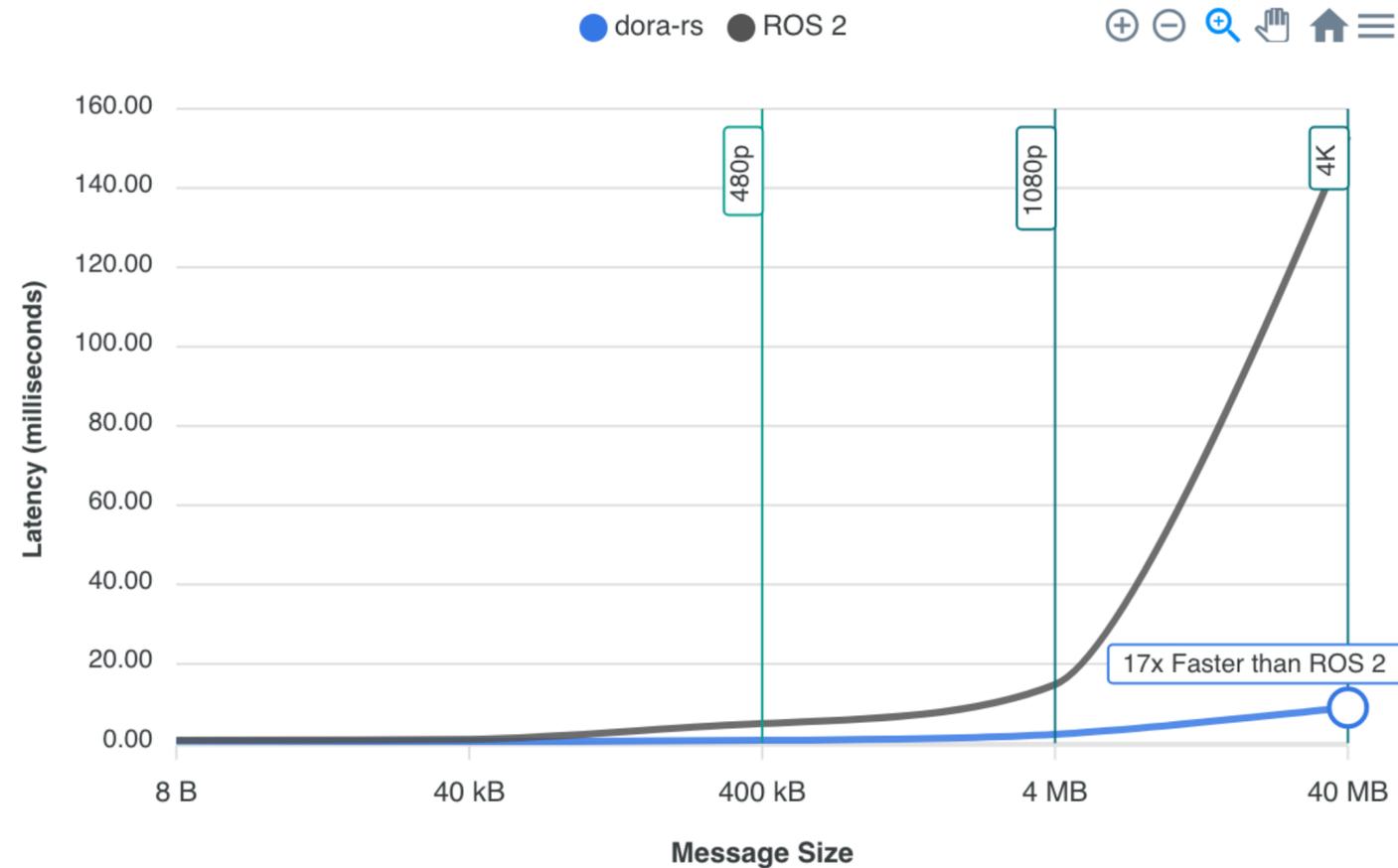


⋮

COMMUNICATION SPEED

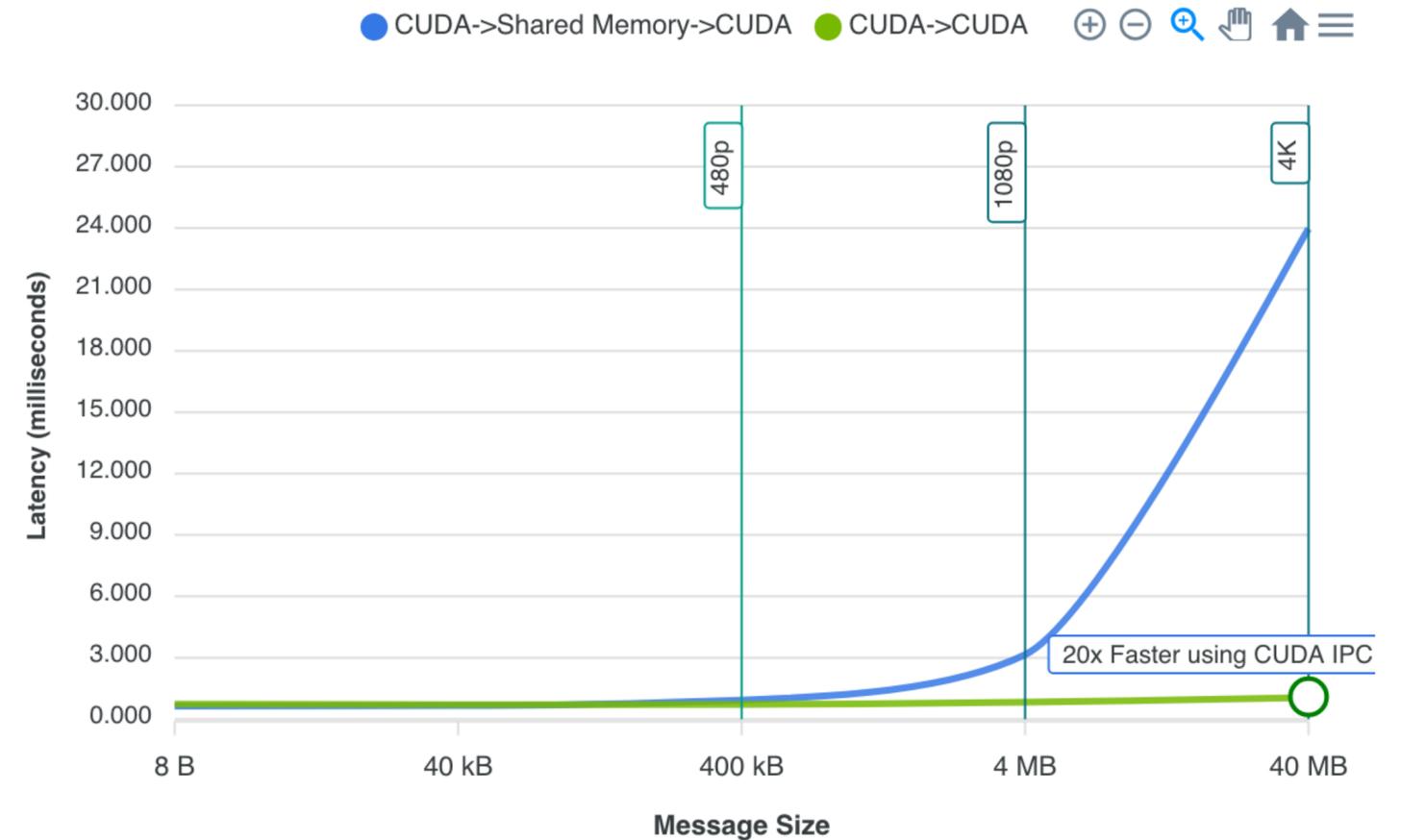
Dora CPU Latency (Lower is better)

Python API Rust API C/C++ API

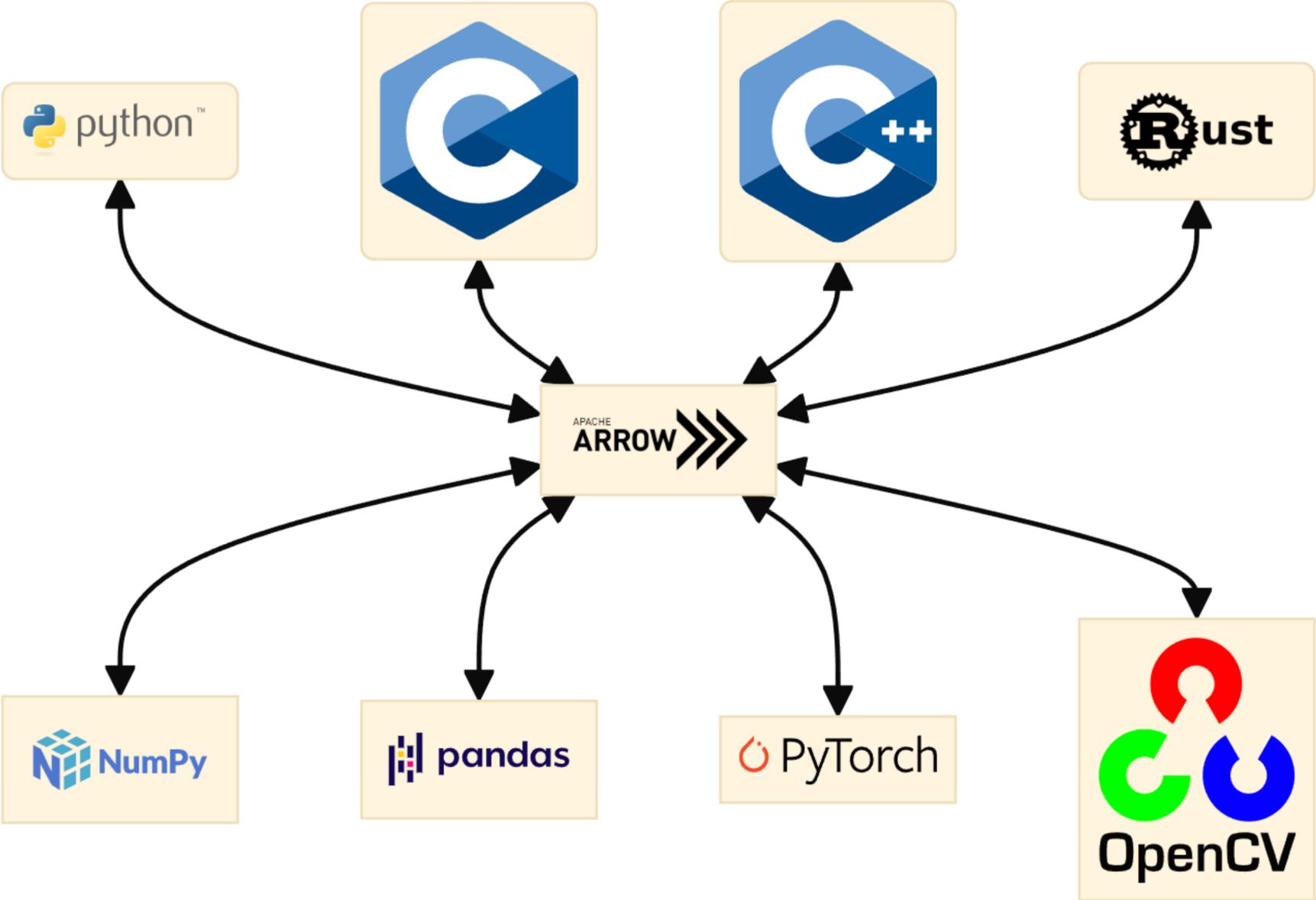


Dora GPU Latency (Lower is better)

PyTorch CUDA



APACHE ARROW FORMAT ENABLING ZERO-COPY FOR BOTH CPU, GPU, NPU...



DEMO TIME

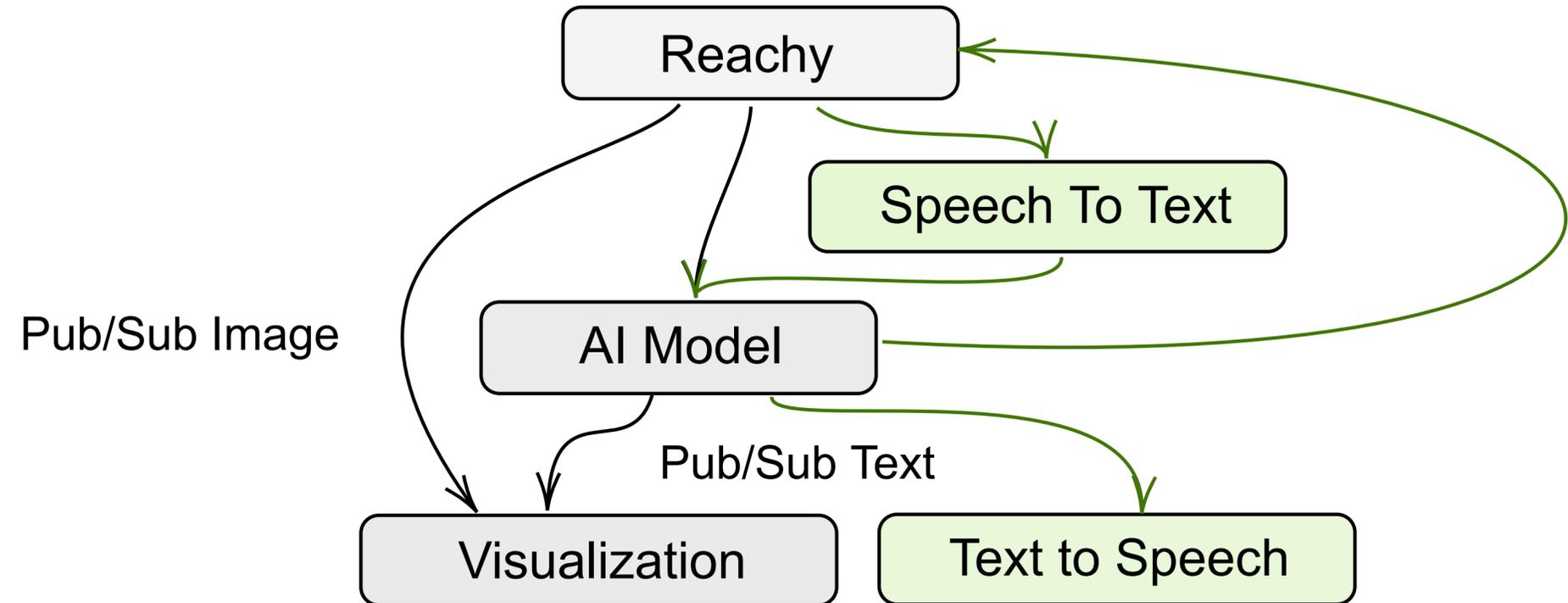
```
nodes:
- id: reachy
  build: pip install dora-reachy2
  path: dora-reachy2
  inputs:
    tick: dora/timer/millis/50
+   action: dora-qwenvl/action
  outputs:
    - image

+ - id: dora-distil-whisper
+   build: pip install dora-distil-whisper
+   path: dora-distil-whisper
+   inputs:
+     input: dora-vad/audio
+   outputs:
+     - text

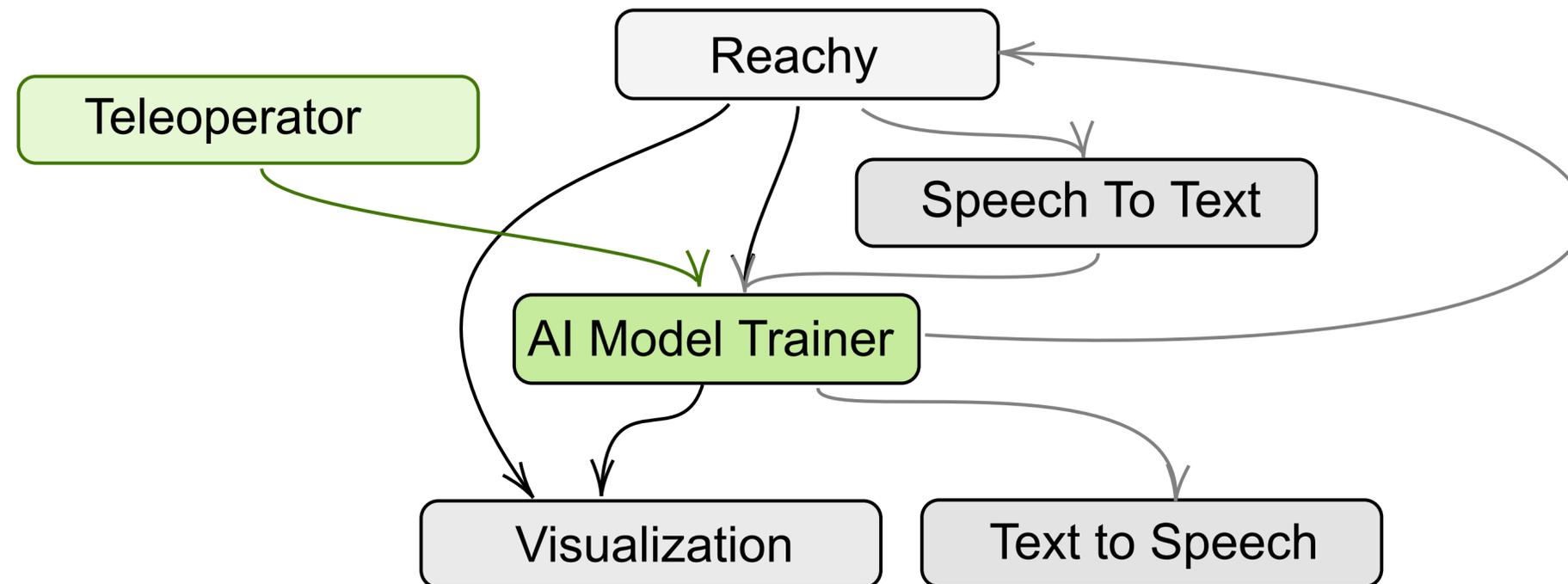
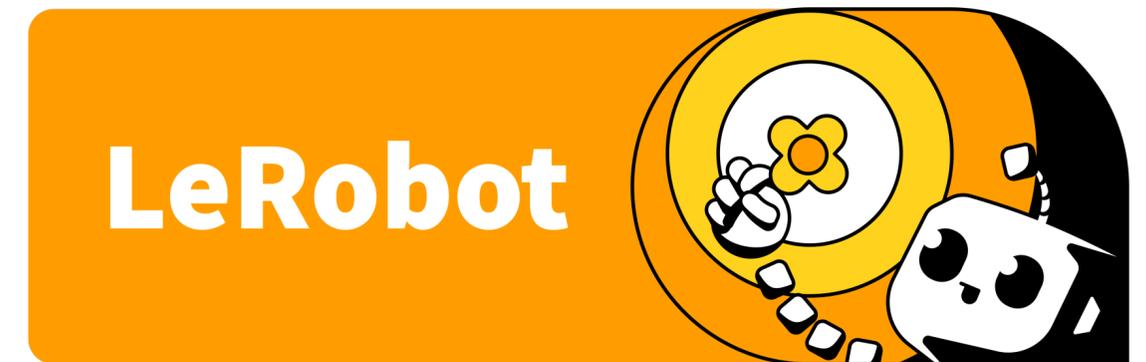
- id: dora-qwenvl
  build: pip install dora-qwenvl
  path: dora-qwenvl
  inputs:
    image: camera/image
+   text: dora-distil-whisper/text
  outputs:
    - text
+   - action

- id: plot
  build: pip install dora-rerun
  path: dora-rerun
  inputs:
    image: camera/image
    text_qwenvl: dora-qwenvl/text

+ - id: dora-outtetts
+   build: pip install dora-outtetts
+   path: dora-outtetts
+   inputs:
+     text: dora-qwenvl/text
```



DATA COLLECTION AND TRAINING CODE CAN BE ADDED SUPER EASILY

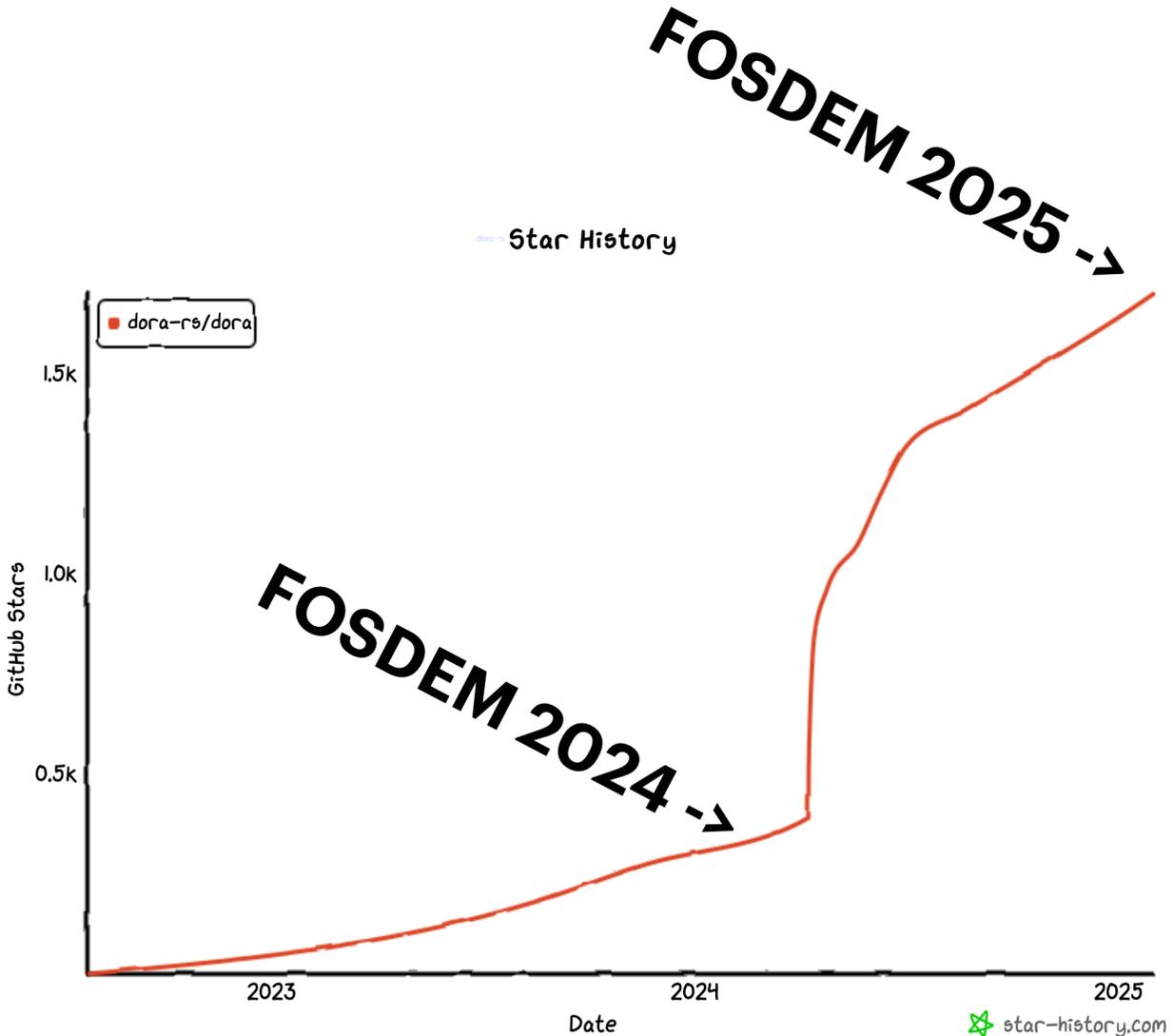


WHAT'S NEXT?

- Adding more models!
- Adding more robots!
- Adding more demos!
- Adding more latency optimization!
- Making dora more mature!



THANKS FOR LISTENING



dora-rs

