Unleashing Bidirectional Charging

Protocols, Challenges, and Strategies with EVerest



About me

Andreas Heinrich @andistorm

Background in electrical engineering Working @ PIONIX on EVerest since 2021



PIONIX

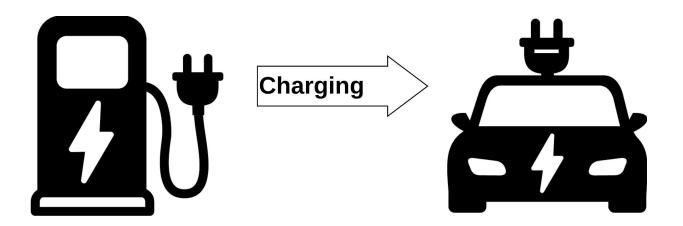


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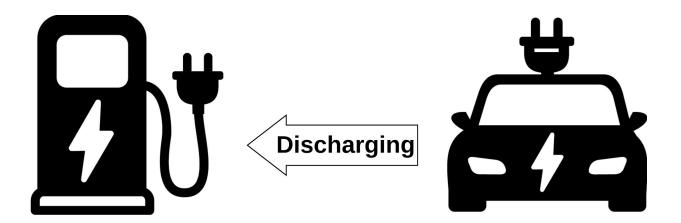
- What is bidirectional charging and why should I do it?
- Charging and Discharging Strategies
- The entire impact chain of bidirectional charging
 - EEBUS
 - ISO 15118
 - OCPP
- Energy Management in EVerest
- Conclusion



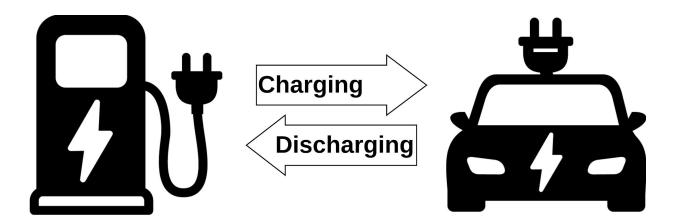




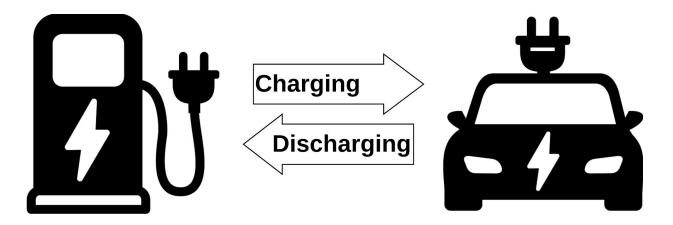












Bidirectional Charging



Why should I do Bidirectional Charging?



Why should I do bidirectional charging

1 Climate Change → We need an energy transition
2 Renewable Energies → More solar & wind power integration
3 Decentralized Smart Grid → Small producers, flexible energy use
4 Grid Stabilization → Balancing fluctuations, supporting stability

Solution → Charge when electricity is cheap
✓ Emergency Power Supply → Energy security for your home
EV as Power Bank → Energy at camping ground





Fast Charging



Electric Vehicle

Minimal Charging Power	2,3 kW
Maximal Charging Power	50 kW
Battery Size	75 kWh





Charging and Discharging Strategies Fast Charging

Arrival Time	0 h
SOC at 0h	10 kWh (~13%)
External Restriction after 30 min	20 kW
Target SOC	75 kWh (100%)

Goal:

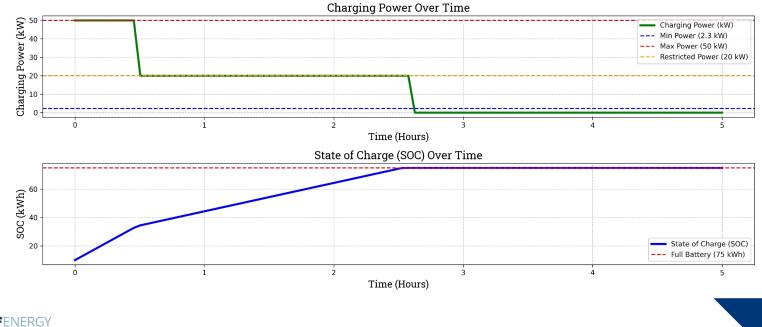
Charge EV as fast as possible

Strategy:

Charge with maximal available power until EV reaches SOC of 75 kWh (100%)



Charging and Discharging Strategies Fast Charging



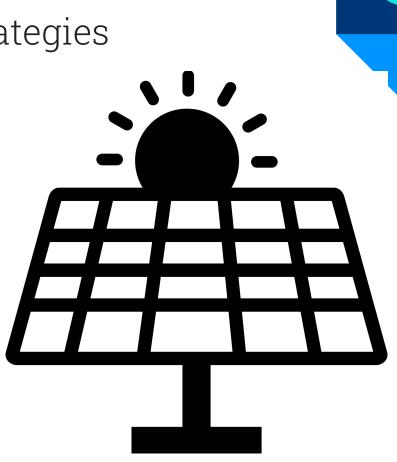


Optimize PV consumption with other consumers



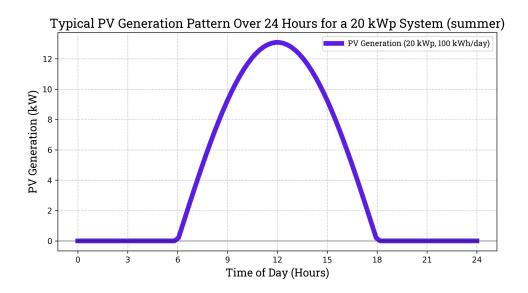
Photovoltaic System

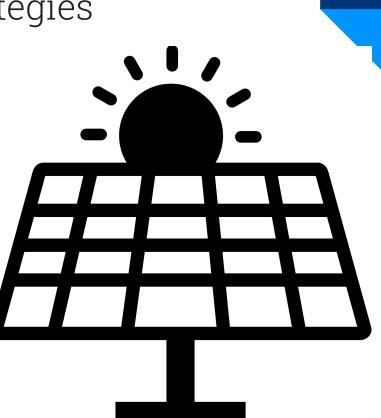
Peak Power	20 kWp	
Daily Energy Yield (summer)	100 kWh/day	





Charging and Discharging Strategies Photovoltaic System







Optimize PV consumption with other consumers

Arrival Time	11 h
SOC at 11h	10 kWh (~13%)
Max Charging Power	20 kW

Goal:

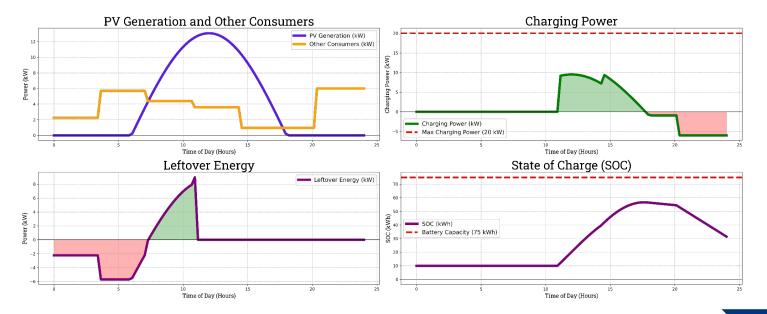
Use as much PV produced energy as possible

Strategy:

Charge with leftover_power = pv_production - other_consumers Discharge if leftover_power < 0 kW



Optimize PV consumption with other consumers

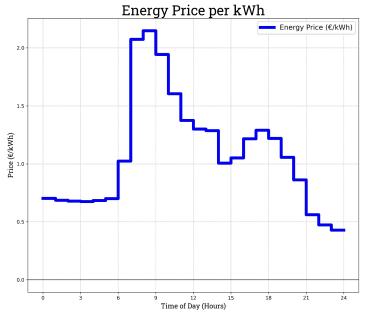




Price Optimization with fixed departure time



Energy Market







Price Optimization with fixed departure time

Arrival Time	10 h
SOC at 11h	10 kWh (~13%)
Max Charging Power	20 kW
Planned Departure Time	22h
Target SOC	75 kWh (100%)

Goal:

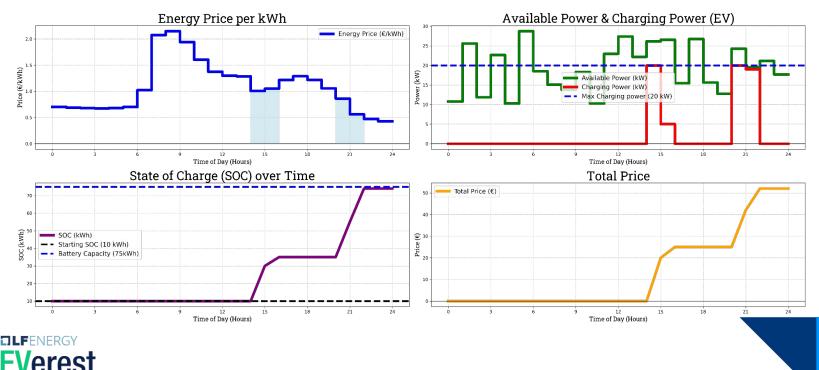
Charge the EV until planned departure time as cheap as possible

Strategy:

- 1. Checkout energy prices until departure time
- 2. Plan charging curve
- 3. Charge in cheapest intervals



Price Optimization with fixed departure time



Grid Support



Charging and Discharging Strategies Grid Support

Arrival Time	10 h
SOC at 11h	50 kWh (~67%)
Max Charging Power	30 kW
Minimal SOC	30 kWh
Maximal SOC	70 kWh

Goal:

Use the EV to stabilize the energy grid

Strategy:

Charge, if grid produces too much energy.Discharge, if grid produces too less energy

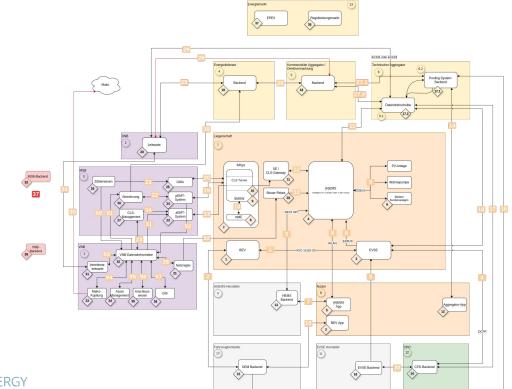


System Architecture

the entire impact chain of bidirectional charging



System Architecture

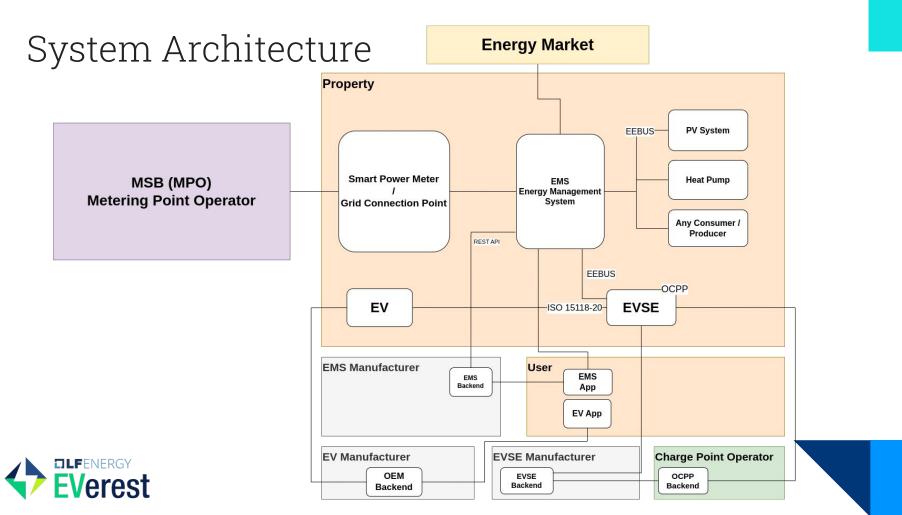


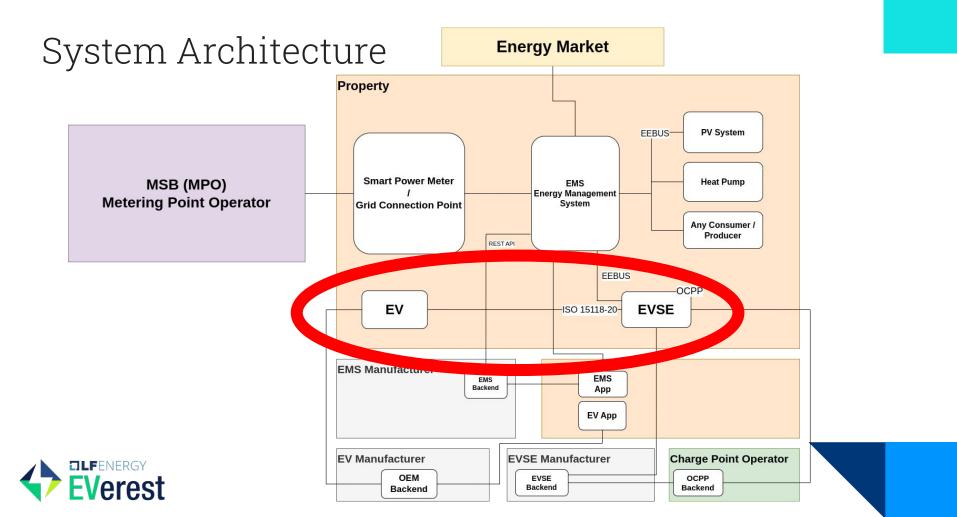


Gefördert durch:

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System Architecture - ISO 15118

- Communication Interface between EV and EVSE
- Defines Procedure of Charging Session
- Provides tooling for
 - Smart Charging
 - Bidirectional Charging

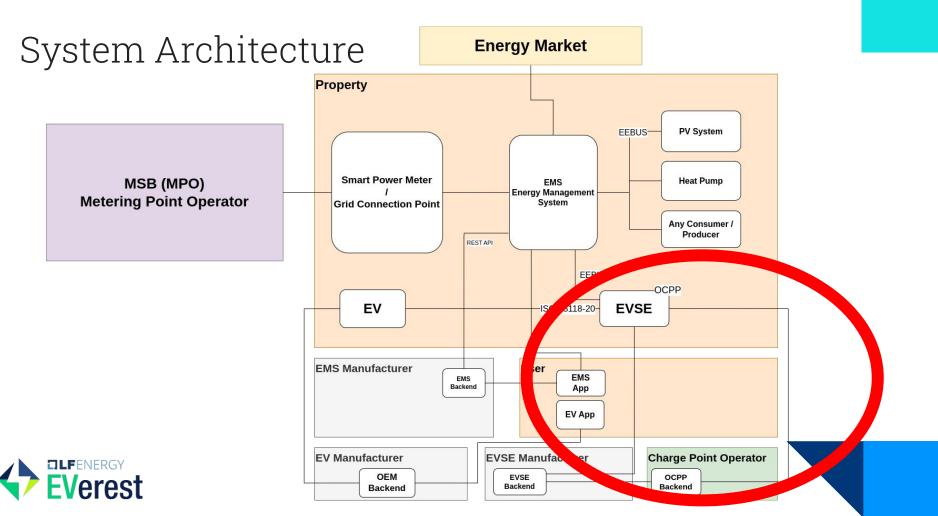
ISO 15118



System Architecture - ISO 15118

	DIN 70121	ISO 15118-2	ISO 15118-20
Start / Stop			
AC	×		
DC			
AC Bidi	×	×	
DC Bidi	(🗙)*	(×)*	
Smart Charging	×	×	
Pause / Resume	×	×	





System Architecture - OCPP

What is OCPP?

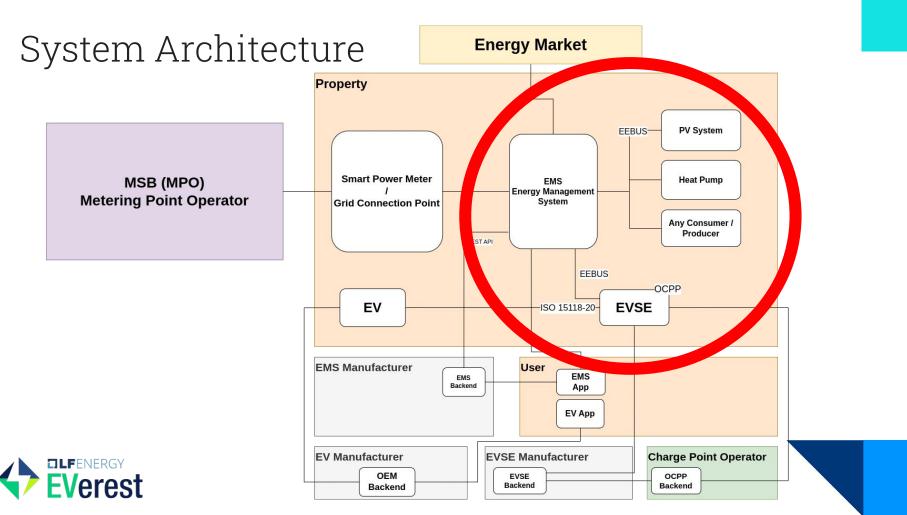
• Open standard protocol for communication between EV charging stations and central systems

What Does OCPP 2.1 Bring?

- New Features for Smart Charging
- Support for bidirectional charging







System Architecture - EEBUS

- Communication Interface for Energy Management
- Enables interaction with grid
- Defines device behaviour within energy management





System Architecture - EEBUS

Use Case: Limitation of Power Consumption

Control active power consumption limit



Figure 1: High-Level Use Case functionality overview



Source: <u>www.eebus.org</u>, <u>www.eebus.org/terms-of-use/</u>

System Architecture - EEBUS

Use Case: Coordinated EV Charging

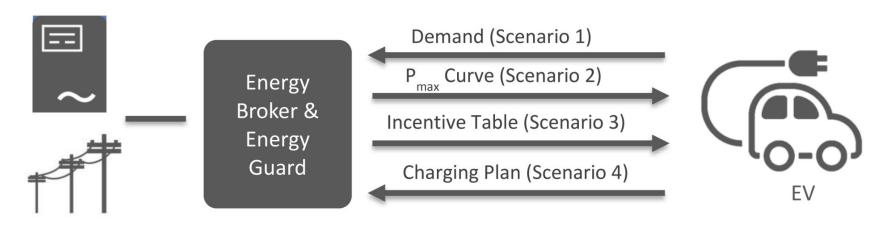


Figure 1: High-Level Use Case functionality overview



Source: <u>www.eebus.org</u>, <u>www.eebus.org/terms-of-use/</u>

System Architecture - EEBUS

Use Case: Optimization of Self-Consumption



Figure 1: High-Level Use Case functionality overview



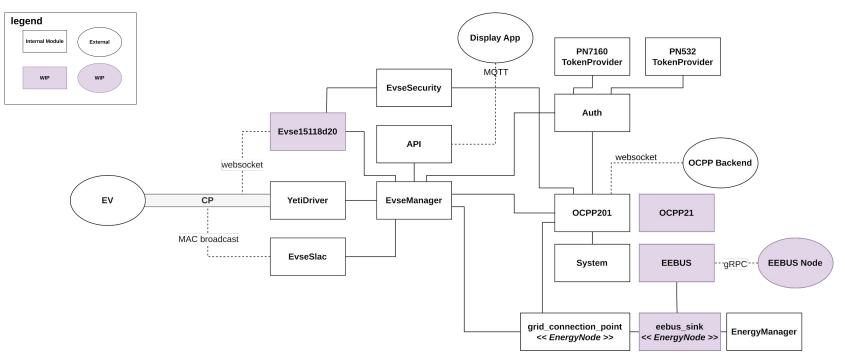
Source: <u>www.eebus.org</u>, <u>www.eebus.org/terms-of-use/</u>

Energy Management in EVerest

EVerest's internal architecture

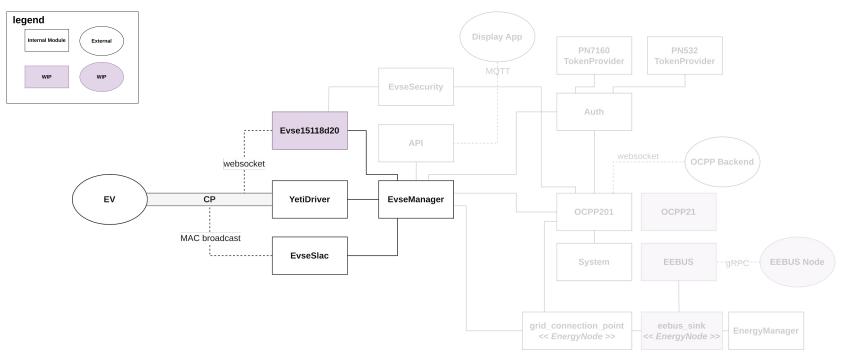


EVerest's internal architecture



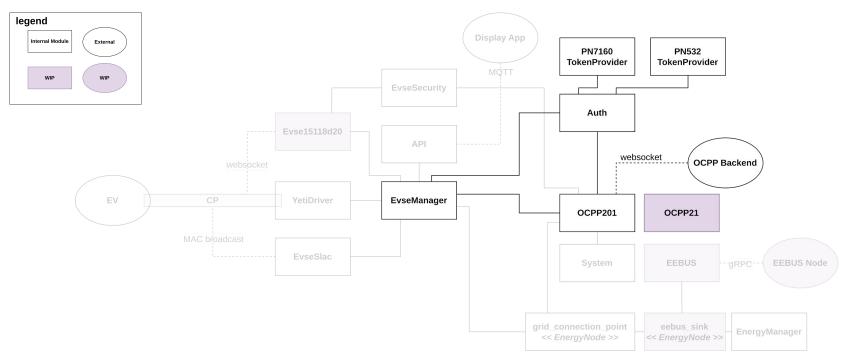


EVerest's internal architecture - ISO 15118



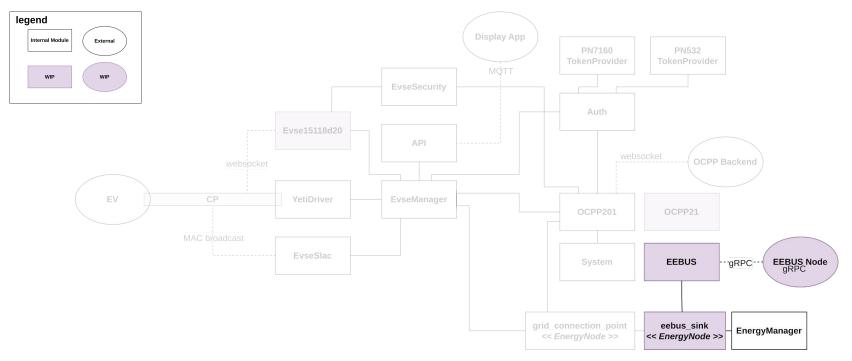


EVerest's internal architecture - OCPP



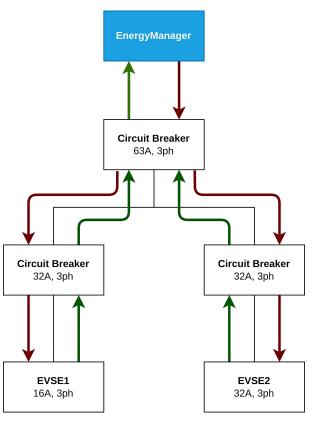


EVerest's internal architecture - EEBUS



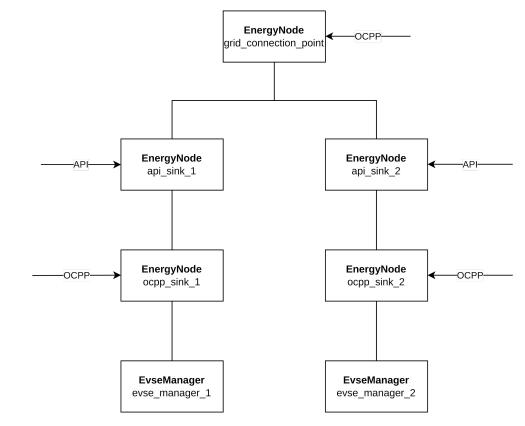


Energy Management inside EVerest



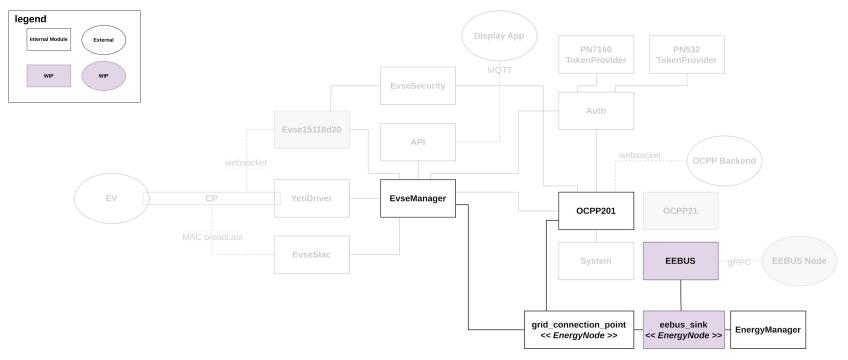


Energy Management inside EVerest





EVerest's internal architecture - Energy Tree





Conclusion



Today's Problems



Conclusion - Today's Problems

EVs and EVSEs in the field don't speak ISO 15118-20

- There are no publicly known EVs that fully implement ISO 15118-20
 - There are a couple of proprietary solutions to enable bidirectional charging
- There are only a few charging stations implementing ISO 15118-20

We continuously test the cars available on the market, see https://github.com/EVerest/logfiles



Conclusion - Today's Problems

Open Standards doesn't mean Open Implementations

- By default, there are no open source feature-complete implementations of protocols like OCPP, ISO 15118, or EEBUS.
- Protocols like EEBUS come with a lot of overhead and do not allow for a simple implementation

EVerest targets to implement those protocols or to integrate existing open implementations



Open Software



EVerest

- Open Source implementations are included in EVerest
 - DIN 70121
 - ISO 15118-2
 - o libiso15118
 - ISO 15118-20 EVSE side (WIP)
 - ISO 15118-20 EV side for testing (WIP)
 - libocpp
 - OCPP 1.6
 - OCPP 2.0.1
 - OCPP 2.1 (WIP), already first charging sessions



Other Open Source Projects

- Open Source implementations that are integrated in EVerest
 - EEBUS enbility/eebus-go (integration is WIP)
- Open Source implementation for OCPP backend
 - CitrineOS (2.0.1 & 1.6 wip)
 - o steve (1.6)
 - o maeve (1.6 & 2.0.1)



Hardware Running EVerest



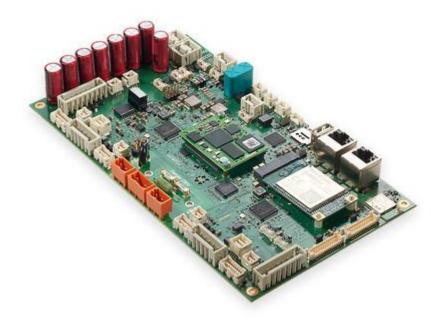
Known EVerest based charger

- Mahle chargeBIG
- Qwello CP21 & CP22
- Pod Point Solo 3s
- Enteligent TLCEV
- Voltpost
- Qwello Retrofit Kits
- Jule (at least for testing)

More than 10.000 chargers in the field at private locations



phyVERSO®-EVCS

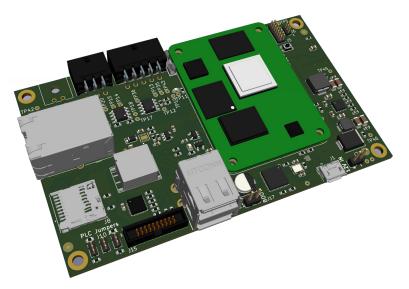


- Charge Controller for AC/DC (Dual Port)
- Bidirectional Charging
- Runs EVerest (Linux based)
- Linux is Yocto based
- Ethernet, WLAN, BLE, LTE, Modbus, CAN
- Dual-Display via LVDS
- Available at <u>https://www.phytec.de/produ</u> <u>kte/fertige-geraete-oem/phyv</u> <u>erso-evcs</u>





YAK

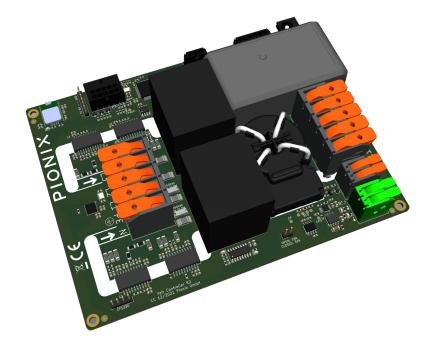


- Raspberry Pi CM4 carrier board
- CAN, RS485, UART, USB, LAN
- Display connector
- PLC modem
- Runs EVerest (Linux based)
- Open Hardware: <u>https://github.com/PionixPublic/</u> <u>reference-hardware</u>
- Available at <u>https://shop.pionix.com/products/y</u> <u>ak-platine-kit</u>





YETI



- 2x 40A AC relais with feedback
- RCD, AC power meter
- CP signal generation and processing
- Full AC "powerpath"
- DC is possible
- Responsible for safety: instance who decides to switch on relays
- Open Hardware and Firmware: <u>https://github.com/PionixPublic/</u> <u>reference-hardware</u>
- Available at <u>https://shop.pionix.com/products</u> <u>/yeti-platine-kit</u>





Join the Movement – Get Involved!



Low entry barrier

Multiple Open Source projects to contribute to

Join our Working Group Calls – Open for everyone

Help shape the future of energy management & EV charging

Bring your ideas, ask questions, and start contributing!



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Q&A session in the hallway



Thanks

