

# Robotics and Simulation devroom

- O 2nd February, 2025
- → fosdem.org/2025/schedule/track/robotics/

#### Who are we

Arnaud Taffanel (Bitcraze)

Lucas Chiesa (Ekumen)

Fred Gurr (Eclipse Foundation)



Mat Sadowski (Weekly Robotics)

Kimberly McGuire (formerly Bitcraze)

### Robotics and Simulation devroom (short) history

- Open Source Robotics Bird of Feather organized last year at Fosdem 2024
  - Confirmed interest and allowed to identified interested people
  - Impromptu lightning talk/project showcase!
- First Robotics and Simulation devroom at Fosdem!
  - Already much more talk proposal than we had spot for
- Hopefully not the last one :-)

### Why Robotics at FOSDEM?

- A lot of the robotic ecosystem is Open-Source
- Already quite some Robotics talk at Fosdem over the years
- Foster communication between projects
- Simplify discovery of projects in the space
  - and Identify missing pieces!

### Some open-source robotics







**ARGoS** Large-scale robot simulations

























**MRPT** 

#### What comes next?

- Robotics and Simulation devroom at FOSDEM 26!
- Any interest for a framework/project independent Robotics community?

[matrix]

#2025-robotics:fosdem.org

## Schedule

#### **Lightning Talks**

**Long Talks** 

**Lightning Talks** 

vent	Speakers	Start	End
Sunday			
Welcome to the Robotics and Simulation devroom	Arnaud Taffanel	13:15	13:20
PyCRAM - A Framework for Cognitive Robot Control	Jonas Dech	13:20	13:25
All my frustrations with ROS summed up in 5 minutes	Roland Meertens	13:25	13:30
Building a robot powered with Raspberry pis and Arduinos from a super fast Traxxas RC car	Loïc Vigneron	13:30	13:38
Accelerating robotics development through simulation	Ignacio Davila Gallesio, Agustin Alba Chicar	13:40	14:0
O3DE: Creating realistic simulations with open-source game engine	Jan Hanca	14:10	14:3
Repurposing Valve's SteamVR 2.0 Technology to Develop an Open-Source, Low-Cost Motion Capture System for Robotics	Said Alvarado-Marin	14:40	15:0
Eclipse Zenoh: Understanding the Protocol and its Potential in Robotic	Julien Enoch	15:10	15:3
BTstudio, a web tool for programming robots with Behavior Trees	JoseMaria Cañas Plaza, Javier Izquierdo	15:40	16:0
ArduPilot : Trusted, Versatile and FOSS autopilot for all and everything	PIERRE KANCIR	16:10	16:3
Whales use Lighthouses too: Open source positioning for open source robots	Michel Hidalgo, Lucas Chiesa	16:40	16:4
Build, Launch, and Soar with Dronecode: The infrastructure ecosystem for the development of autonomous aerial robotics.	Ramon Roche	16:45	16:5
Integration and unit testing in ROS 2	Arne Baeyens	16:50	16:5
ROS in transition: a new organizational path under the Open Source Robotics Alliance	Jose Luis Rivero	16:55	17:00