Bringing a new API to KiCad

First, some background

The era of SWIG







SWIG (in KiCad) Challenges

- 1. The interface is fragile
- 2. Modern C++ doesn't always play nice
- 3. Slows down the build
- 4. Python plugins can completely break KiCad

Packaging Challenges

- 1. wxPython and wxWidgets
- 2. Bundled Python interpreter
- 3. Dependency management

Developer Experience Challenges

- 1. Environment your code runs in is hard to re-create in a development context
- 2. KiCad Python Console is... okay

How We Didn't Fix It

Make a real API layer in C++; have SWIG wrap that.

- Minimal paradigm shift! Not that risky.
- Doesn't solve most of the problems

Make a real API layer in C++; have Pybind11 wrap that.

- (Maybe) solves a few more problems!
- Still doesn't solve the rest of them 😕

Introducing the IPC API

Key Principles

- 1. Be robust against code evolution in KiCad itself
- 2. API users should not have direct access to KiCad internal state (run in external process)
- 3. Developer experience is important, both for the KiCad team and API users



Transport: Why Nanomsg-NG (NNG)?

- Simple to implement
- Target native IPC mechanisms (UNIX sockets, named pipes on Windows) with the same code
- Good availability across platforms and languages
- Also considered: ZeroMQ, gRPC, D-Bus

Protocol: Why Protocol Buffers (protobuf)?

- The API is the message definitions
- *When used well*, allows for API evolution over time and cross-version compatibility
- Alternatives are either not as widely used and supported, or don't solve the same problems

```
message Vector2
  int64 x_nm = 1;
  int64 y_nm = 2;
}
message Box2
  kiapi.common.types.Vector2 position = 1;
  kiapi.common.types.Vector2 size = 2;
}
```

```
// returns kiapi.common.types.Box2
message GetTextExtents
{
    kiapi.common.types.Text text = 1;
}
```

```
message ApiRequest
{
    ApiRequestHeader header = 1;
    google.protobuf.Any msg = 2;
}
```

```
message ApiResponse
{
    ApiResponseHeader header = 1;
    ApiResponseStatus status = 2;
```

}

```
google.protobuf.Any msg = 3;
```

Plumbing it in to KiCad

KiCad's Event Handling, basically









API Events Are Synchronous!



 Plugins can control their own undo/redo transactions

 The API will sometimes reject a command and say "I'm busy"

Using the API from Python

\$ pip install kicad-python

https://gitlab.com/kicad/code/kicad-python

		Preferences	
>	Common KiCa Mouse and Touchpad Hotkeys Cymbol Editor Schematic Editor	KiCad API When the KiCad API is enabled, plugins and other software running on this computer can connect Enable KiCad API Listening at ipc:///tmp/kicad/api.sock	et to KiCad.
> > >	 Footprint Editor PCB Editor Display Options Grids Origins & Axes Editing Options Colors Plugins 3D Viewer Gerber Viewer Drawing Sheet Editor Packages and Updates Plugins 	Python Interpreter Path to Python interpreter: /Users/jon/src/kicad-mac-builder/build/python-dest/Lit Browse Found Python 3.9.13	Detect Automatically
	Reset Plugins to Defaul	Reveal Preferences in Finder	Cancel OK

```
from kipy import KiCad
from kipy.board_types import (
    BoardLayer,
    Zone
from kipy.common_types import PolygonWithHoles
from kipy.geometry import PolyLine, PolyLineNode
from kipy.util import from_mm
if name ==' main ':
   kicad = KiCad()
    board = kicad.get board()
   outline = PolyLine()
   outline.append(PolyLineNode.from xy(from mm(100), from mm(100)))
    outline.append(PolyLineNode.from_xy(from_mm(110), from_mm(100)))
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    polygon = PolygonWithHoles()
    polygon.outline = outline
    zone = Zone()
    zone.layers = [BoardLayer.BL F Cu, BoardLayer.BL B Cu]
    zone.outline = polygon
    board.create items(zone)
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New Python plugin launching system

- Virtual environments per-plugin
- Automatic* dependency installation
- KiCad tells the plugin how to connect to the API
- *Bonus*: also supports non-Python plugins!

*as long as binary wheels for your platform are available 😅

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Roadmap

- Footprint editor integration + wizards
- Plotting/exporting (use kicad-cli today)
- Headless operations
- Schematic and symbols
- Your idea here?

https://dev-docs.kicad.org





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