

Running Mainline Linux on the Jolla C2

FOSS on Mobile - FOSDEM 2026

Affe Null

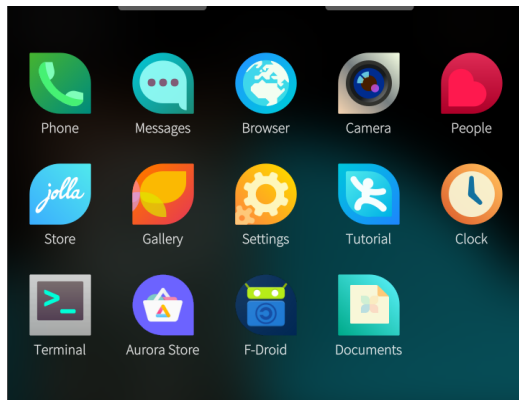
January 31, 2026

What is the Jolla C2?

- ▶ Jolla smartphone released in 2024
- ▶ “Reference device” for Sailfish OS
- ▶ Partnership with Reeder (Turkish company)
- ▶ Mostly identical to Reeder S19 Max Pro S
- ▶ Based on Unisoc Tiger T606 (UMS9230) SoC

How does the phone run Linux?

- ▶ Shell access available in developer mode



How does the phone run Linux?

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[defaultuser@JollaC2 ~]$ uname -a  
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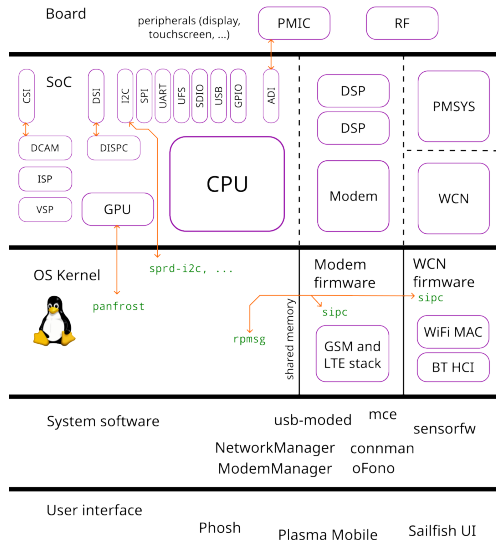
- ▶ typical situation with downstream drivers made for Android
- ▶ Sailfish OS uses Android vendor HAL via libhybris (as expected)
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 - ▶ roots in Nokia's Meego project
 - ▶ closer to traditional GNU/Linux userspace

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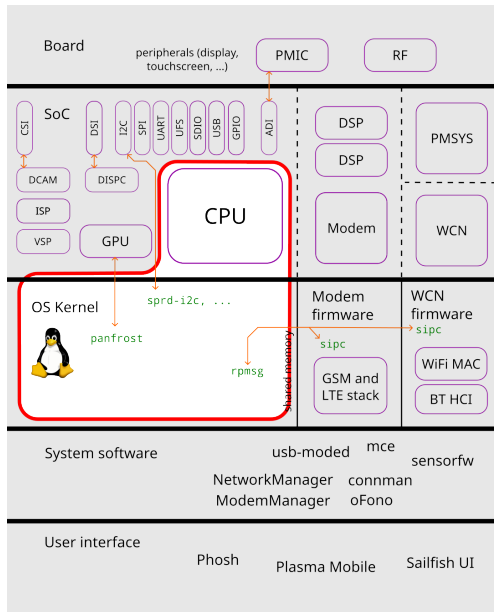
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- ▶ Sailfish OS uses Android vendor HAL via libhybris (as expected)
- ▶ However, it does not strictly depend on libhybris or Android
 - ▶ roots in Nokia's Meego project
 - ▶ closer to traditional GNU/Linux userspace
- ▶ Why not a mainline kernel?
 - ▶ a few drivers from Unisoc are already upstream
 - ▶ try something new

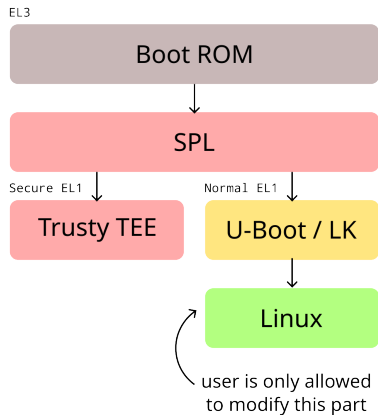
Overview



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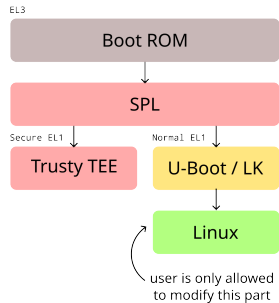
Simplified boot chain



Mainlining - first steps

- ▶ Phone arrived in November 2024
- ▶ Step 1: flashing
 - ▶ spd_dump tool with CVE-2022-38694 exploit

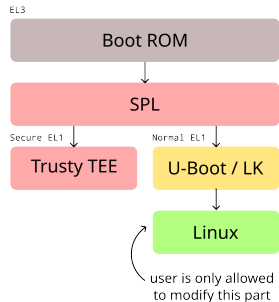
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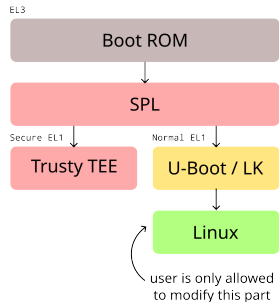
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- ▶ Android bootloader does initial setup
 - ▶ starts display output from memory
 - ▶ powers up internal storage
 - ▶ unfortunately requires dtbo and messes with device tree

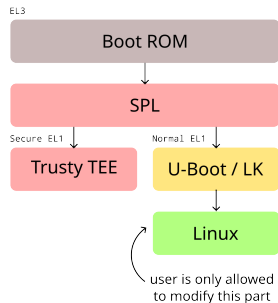
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 - ▶ unfortunately requires dtbo and messes with device tree
- ▶ Chainloading U-Boot to simplify things
 - ▶ ignores Android device tree and provides its own
 - ▶ standard boot process
 - ▶ implement just enough drivers to load kernel

Simplified boot chain

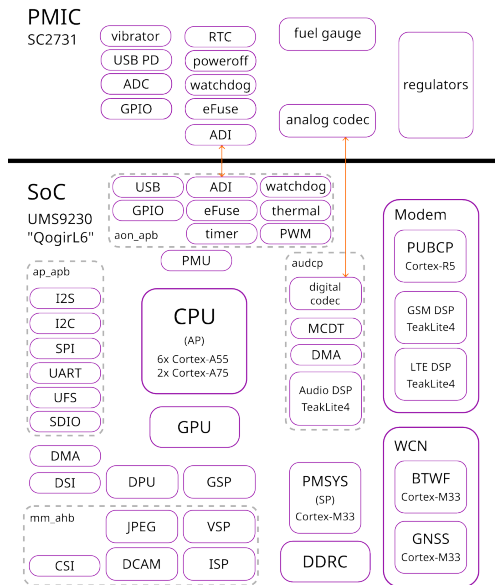


Debugging

- ▶ using UART would require disassembling phone
- ▶ easier to set display pixels in memory
- ▶ simple-framebuffer and simplefb earlycon patch

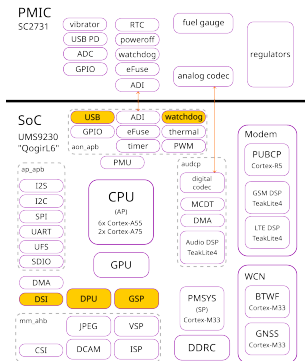
```
[ 0.000000] CPU features: detected: mm errata 110322, 131307, 0r 133023
[ 0.000000] alternatives: applying boot alternatives
[ 0.000000] Kernel command line: root=PARTUUID=7d3d5c60-a593-4afe-ba7e-8896690c7513 ear
lycon=simplefb,0x9e000000,720,1600
[ 0.000000] printk: log buffer data + meta data: 131072 + 450752 = 580824 bytes
[ 0.000000] Dentry cache hash table entries: 1048576 (order: 11, 8388608 bytes, linear)
[ 0.000000] Inode-cache hash table entries: 524288 (order: 10, 4194304 bytes, linear)
[ 0.000000] software IO TLB: area num 8.
[ 0.000000] software IO TLB: mapped [mem 0x00000000fa000000-0x00000000fe000000] (64MB)
[ 0.000000] Fallback order for Node 0: 0
[ 0.000000] Built 1 zonelists, mobility grouping on. Total pages: 2097151
[ 0.000000] Policy zone: Normal
[ 0.000000] mem auto-init: stack:all(zero), heap alloc:off, heap free:off
[ 0.000000] SLUB: HWalign=64, Order=0-3, MinObjects=0, CPUs=8, Nodes=1
[ 0.000000] ftrace: allocating 47412 entries in 186 pages
[ 0.000000] ftrace: allocated 186 pages with 5 groups
[ 0.000000] rcu: Preemptible hierarchical RCU implementation.
[ 0.000000] rcu: oRCU event tracing is enabled.
[ 0.000000] rcu: oRCU restricting CPUs from NR_CPUS=512 to nr_cpu_ids=8.
[ 0.000000] oTrampoline variant of Tasks RCU enabled.
[ 0.000000] oRude variant of Tasks RCU enabled.
[ 0.000000] oTracing variant of Tasks RCU enabled.
[ 0.000000] rcu: RCU calculated value of scheduler-enlistment delay is 25 jiffies.
[ 0.000000] rcu: Adjusting geometry for rcu_fanout_leaf=16, nr_cpu_ids=8
[ 0.000000] RCU Tasks: Setting shift to 3 and lim to 1 rcu_task_cb_adjust=1 rcu_task_cp
u_ids=8,
[ 0.000000] RCU Tasks Rude: Setting shift to 3 and lim to 1 rcu_task_cb_adjust=1 rcu_to
sk_cpu_ids=8,
[ 0.000000] NR_IRQS: 64, nr_irqs: 64, preallocated irq: 0
[ 0.000000] GICv3: GIC: Using split EOI/Deactivate mode
[ 0.000000] GICv3: 192 SPIs implemented
[ 0.000000] GICv3: 0 Extended SPIs implemented
```

The UMS9230 chipset



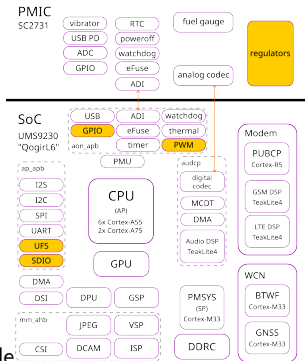
Mainlining - initial bringup

- ▶ Clock driver
 - ▶ already in mainline for older Unisoc SoCs
 - ▶ very similar to downstream
- ▶ USB is hard, but simplifies debugging a lot
 - ▶ PHY init sequence, obscure registers
 - ▶ old MUSB controller with additional DMA quirks
 - ▶ messy code both upstream and downstream
 - ▶ transfers sometimes get stuck in host mode
- ▶ Watchdog
 - ▶ phone reboots, seemingly no effect from driver (more on this later)
- ▶ Display driver
 - ▶ replaces simple-framebuffer
 - ▶ usually complicated
 - ▶ existing drivers/gpu/drm/sprd from 2021
 - ▶ many fixes and UMS9230 support added



Mainlining - peripherals (1)

- ▶ SC2730 PMIC regulators
 - ▶ required for powering components including storage
 - ▶ MFD driver in mainline since 2021
 - ▶ merged downstream driver and existing SC2731 driver
- ▶ External Storage: SD card
 - ▶ existing driver (mainline since 2018) mostly usable
 - ▶ later fixes for high-speed operation
- ▶ Internal Storage: UFS
 - ▶ existing driver (mainline since 2022) for different SoC is incompatible
 - ▶ bootloader initializes hardware with low clock speed
 - ▶ restarting after clock change requires PHY init sequence
- ▶ GPIO driver (mainline since 2018) worked with almost no changes
 - ▶ some buttons or LEDs, depending on the device
 - ▶ various control pins for peripherals
- ▶ PWM backlight



Mainlining - peripherals (2)

► SC2730 PMIC

- already in mainline: vibrator, fuel gauge, RTC, ADC, ...
- some drivers for older SC2731 PMIC adapted
- bug fixes for fuel gauge driver
- Type-C PD driver adapted from downstream, cleanups needed
- separate watchdog in PMIC enabled on startup

► UART, I2C, SPI

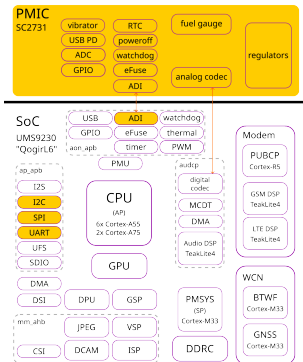
- copy-paste device tree nodes
- match clocks with clock driver

► Charger (device-specific)

- sgm41511 (bq25601 clone, existing driver works)

► Touchscreen driver (device-specific, usually I2C)

- existing mainline drivers
- downstream driver as reference
- icn19916 driver for Jolla C2 was quite easy to write

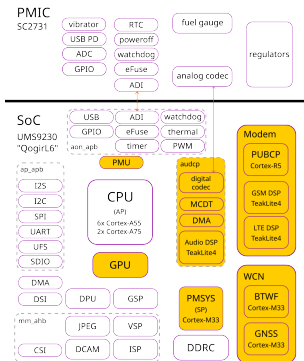


Minimal example

<https://storage.abscue.de/private/zImage/jolla-c2-simple-boot.mp4>

Mainlining - SoC subsystems

- ▶ Power domains: new driver
- ▶ GPU supported by panfrost driver
- ▶ Remoteprocs
 - ▶ using firmware from Android
 - ▶ WCN (BTWF, GNSS) – Cortex-M33
 - ▶ Audio – Ceva TeakLite4 DSP (undocumented architecture)
 - ▶ Modem – Cortex-R5 and two TeakLite4 DSPs
 - ▶ PMSYS aka SP (sensor hub, GNSS, ...) – Cortex-M33
- ▶ SIPC protocol for communication with remoteprocs
 - ▶ shared memory ring buffer, character and packet-based variants
 - ▶ new rpmsg driver
- ▶ PMSYS also responsible for managing PMIC watchdog
 - ▶ watchdog on command needed
 - ▶ intercepts AP watchdog to trigger some kind of crash dump
- ▶ Bluetooth: mostly standard HCI

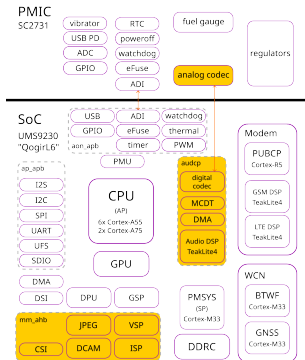


New WiFi driver

- ▶ first version took about one month to develop
- ▶ cfg80211 driver using original firmware
- ▶ downstream driver as reference
- ▶ features implemented:
 - ▶ scanning
 - ▶ regulatory domains
 - ▶ connecting to networks
 - ▶ WPA key management
 - ▶ power saving
- ▶ still not fully working
- ▶ features missing: AP mode, QoS, IBSS, P2P, ...
- ▶ only supports integrated WiFi
 - ▶ some phones use external module via SDIO

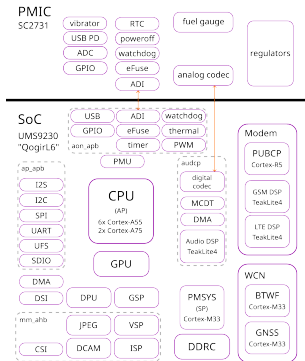
Mainlining steps - multimedia features

- ▶ New drivers needed for almost everything
- ▶ Audio
 - ▶ bootloader starts DSP for some reason
 - ▶ AP ↔ DSP communication
 - ▶ SoC ↔ PMIC link
 - ▶ PMIC analog codec
 - ▶ ALSA machine driver
 - ▶ call audio via codec2codec link
- ▶ Camera
 - ▶ CSI PHY
 - ▶ DCAM: raw capture with some processing
 - ▶ separate ISP: memory-to-memory, debayering, additional processing
 - ▶ open-source driver with list of registers
 - ▶ device-specific sensor drivers
- ▶ Hardware video encoding/decoding
 - ▶ not implemented yet
 - ▶ proprietary



Mainlining steps - more features

- ▶ GNSS: new driver
 - ▶ baseband is part of WCN subsystem
 - ▶ NMEA data generated by PMSYS remoteproc firmware
 - ▶ custom commands for A-GNSS not implemented yet
- ▶ Sensors: new IIO driver
 - ▶ I2C controlled by PMSYS sensor hub
 - ▶ firmware obviously designed with Android in mind
 - ▶ sends floating-point numbers requiring conversion in kernel
- ▶ CPU frequency scaling
 - ▶ implemented in proprietary firmware that runs on the AP
 - ▶ new driver for querying and setting frequencies
- ▶ Other power management features
 - ▶ PSCI suspend worked right away
 - ▶ DVFS implemented in various remoteprocs, not supported yet



Common problems

- ▶ Clock and power domain management
 - ▶ hard to verify without SoC documentation
 - ▶ determining when they are safe to turn off requires testing
 - ▶ some drivers (e.g., IOMMU) keep clocks on all the time
 - ▶ common clock framework can keep power domains on
- ▶ Proprietary remoteproc firmware
 - ▶ undocumented protocols
 - ▶ buggy or Android-oriented behavior
 - ▶ reverse-engineering the binaries is sometimes required
 - ▶ open-source alternatives should be developed, but need a lot of work
- ▶ Upstreaming is slow
 - ▶ should have started earlier

Userspace

- ▶ Power management (autosleep)
 - ▶ mostly works well in Sailfish OS with mce
 - ▶ not really supported in other mobile Linux environments
 - ▶ important events must keep device awake until processed
 - ▶ processing often split across different services
 - ▶ userspace vs kernel-side autosleep
- ▶ Modem
 - ▶ uses AT commands with some quirks
 - ▶ basic oFono driver for Sailfish OS
 - ▶ ModemManager not quite working yet
- ▶ Camera
 - ▶ libcamera fork
 - ▶ will be upstreamed after kernel driver
 - ▶ most camera apps are still very basic
 - ▶ new abstraction library for cameras?

Demo

<https://storage.abscue.de/private/zImage/jolla-c2-kernel.mp4>

Results

- ▶ Mainlining a new SoC is possible!
 - ▶ not everything needs existing upstream support
 - ▶ more opportunities to create simple drivers where none exist yet
 - ▶ downstream was usable as reference
- ▶ Somewhat usable as daily driver
- ▶ Did not take much longer than a year
 - ▶ can be done faster with more time investment
- ▶ Sailfish OS can work without libhybris

Further opportunities

- ▶ Mainline more devices!
 - ▶ new Jolla Phone (2026) with MediaTek SoC
- ▶ upstream more changes
- ▶ fix issues with WiFi
 - ▶ work on new open-source firmware
- ▶ for Sailfish OS:
 - ▶ most userspace components already adapted
 - ▶ Jolla is generally open to contributions as long as they don't break things
 - ▶ reach feature parity
- ▶ for other distributions (e.g., postmarketOS):
 - ▶ implement ModemManager support
 - ▶ improve userspace power management

Thank you for listening!

Here are some links:

- ▶ Kernel fork: <https://codeberg.org/ums9230-mainline/linux>
- ▶ remoteproc firmware prototype: <https://codeberg.org/affenull12345/opencp>
- ▶ Sailfish OS port: <https://forum.sailfishos.org/t/mainline-linux-kernel-for-the-jolla-c2/21382/19>