

vehicle_dynamics_sim

Arne Baeyens

FOSDEM '26

The Experience

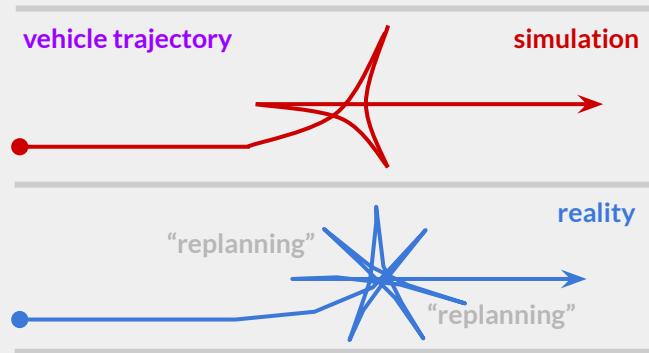


N A V 2

The Experience



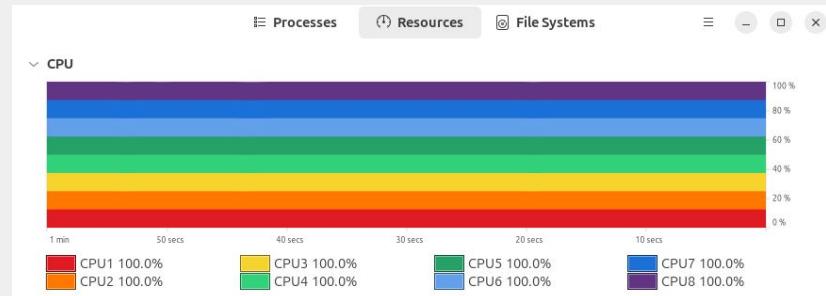
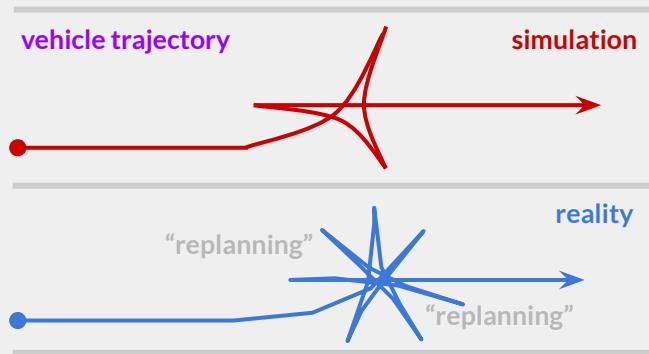
N A V 2



The Experience



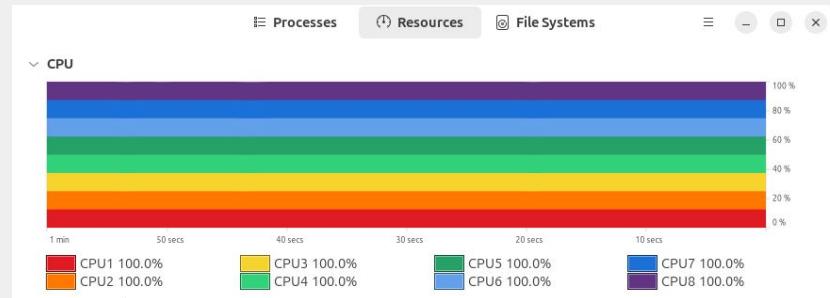
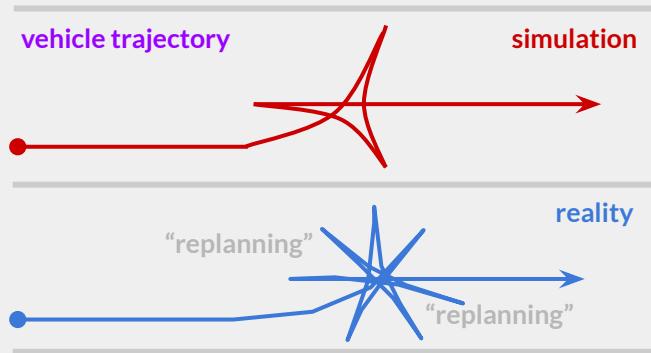
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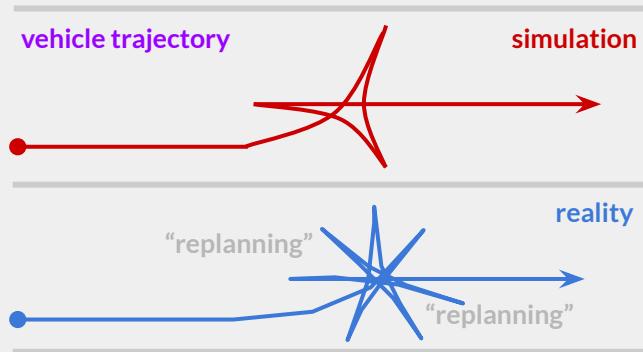
NAV 2



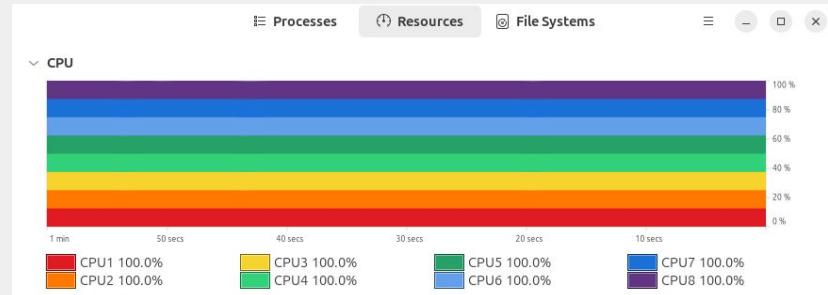
The Experience



NAV 2



- “Simulation is costly”
- “Simulation slows down development”
- “Simulation doesn’t deliver”



What can we change ?

Pain points
and
Ideas

What can we change ?

unrealistic dynamics

good default vehicle models

no custom code required

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? which values ?
all parameters values
easily measurable

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laborious set up

- config through ROS 2 params
 - tests easily parametrized
- REP 105 localization simulation
- Run on wall clock
 - no use_sim_clock:=true

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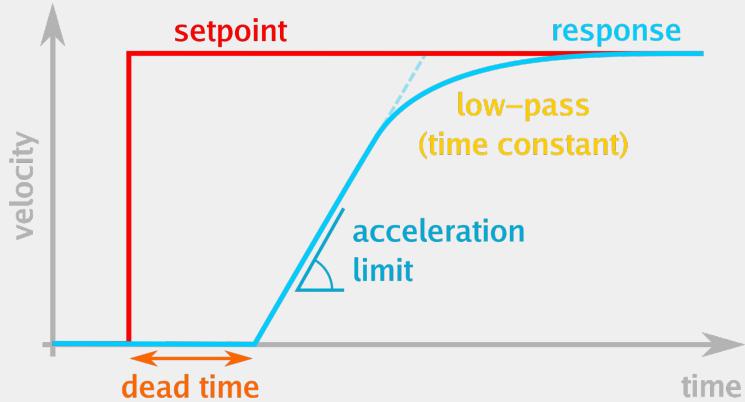
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=> `vehicle_dynamics_sim` <=

What's in a drive model ?



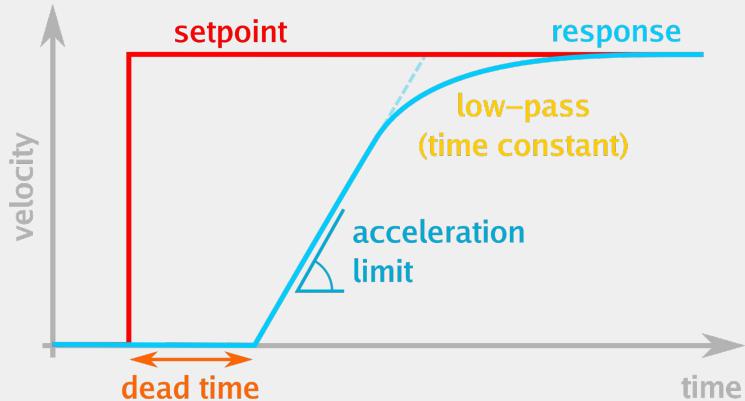
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“Cover key dynamics”

- **dead time**
finite transmission velocity

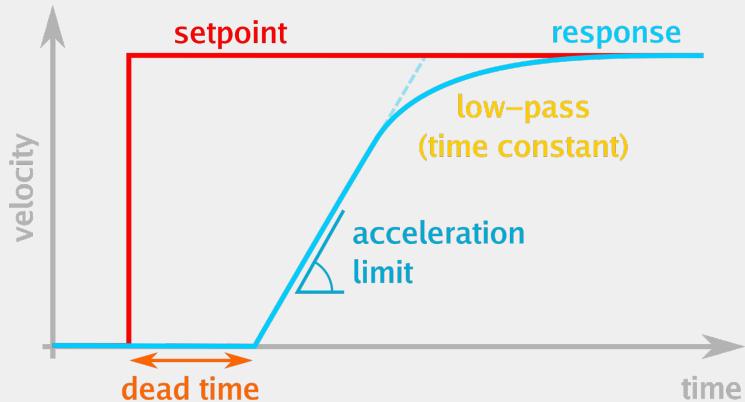
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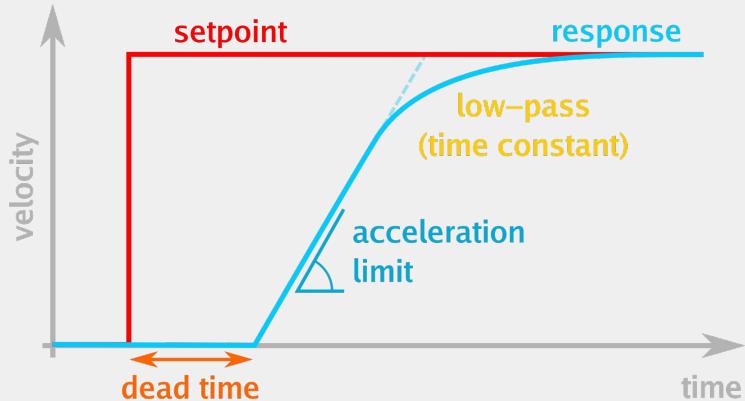
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How to measure **dead time** etc.?

1. Apply step **reference**
2. Measure **response**
3. Read params from graph

Nav2 demo video

vehicle_dynamics_sim

! thanks !

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