

vehicle_dynamics_sim

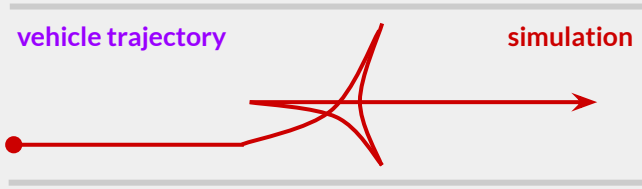
Arne Baeyens

FOSDEM '26

The Experience



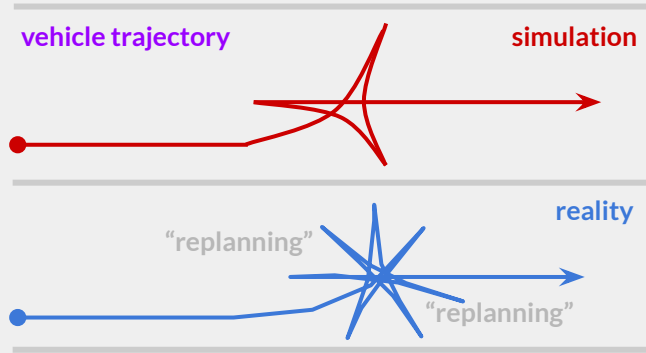
NAV2



The Experience



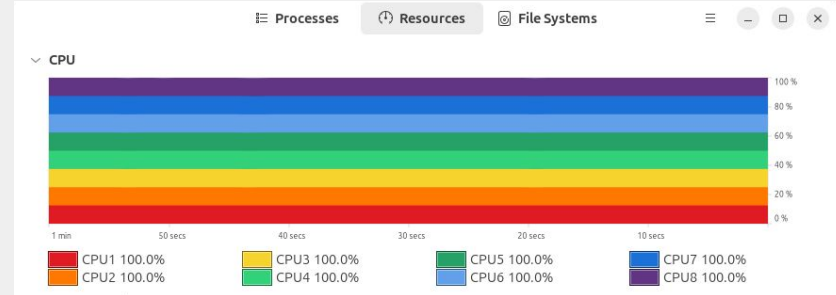
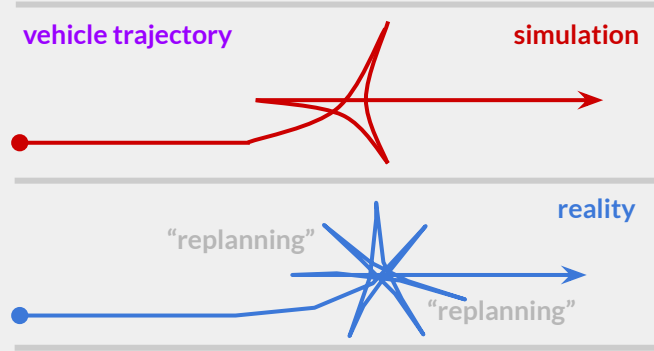
N A V 2



The Experience



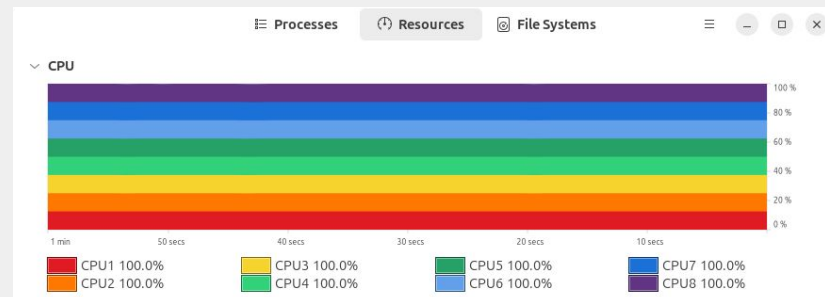
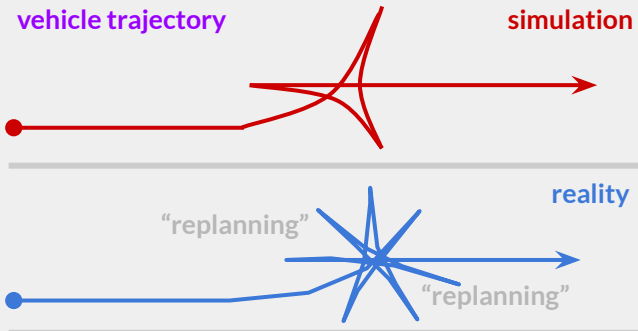
NAV2



The Experience



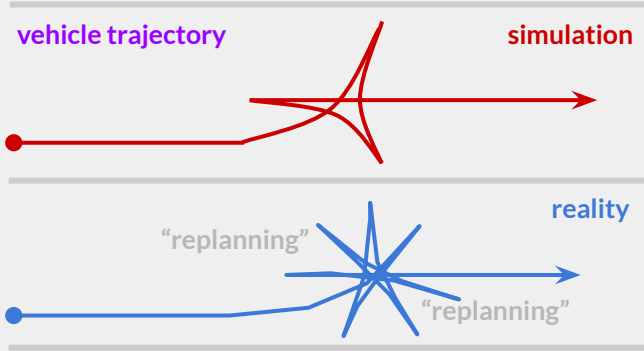
NAV2



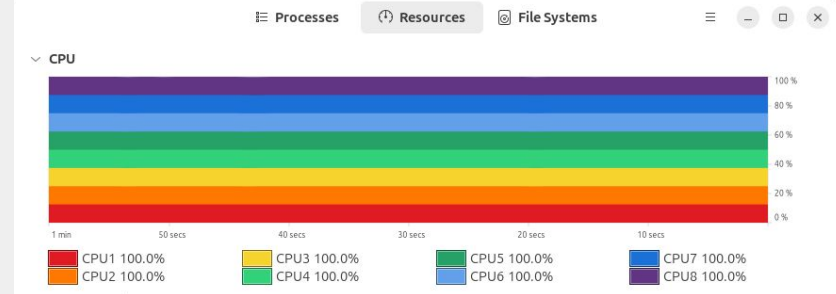
The Experience



NAV2



- “Simulation is costly”
- “Simulation slows down development”
- “Simulation doesn’t deliver”



What can we change ?

Pain points
and
Ideas

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unrealistic dynamics

good default vehicle models

no custom code required

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? which values ?

all parameters values

easily measurable

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laborious set up

- config through ROS 2 params
 - *tests easily parametrized*
- REP 105 localization simulation
- Run on wall clock
 - `no use_sim_clock:=true`

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- ? efficient code ?

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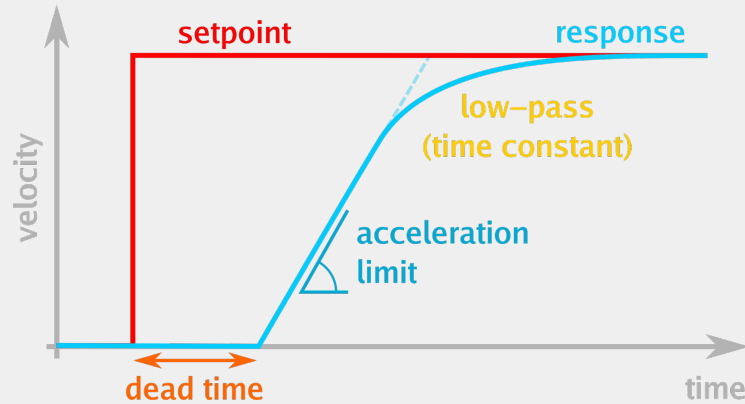
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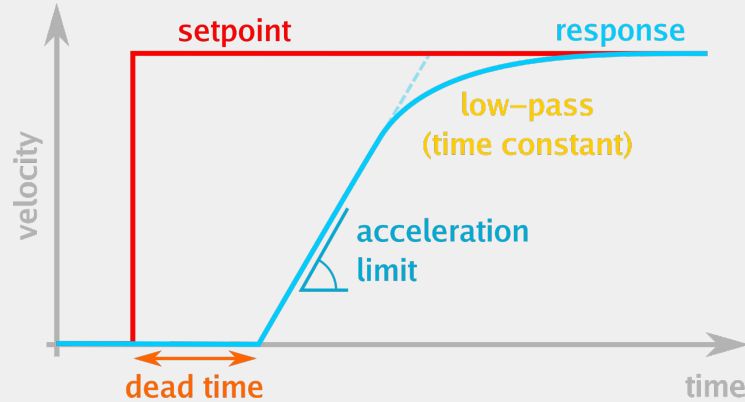
=> vehicle_dynamics_sim <=

What's in a drive model ?

“Cover key dynamics”



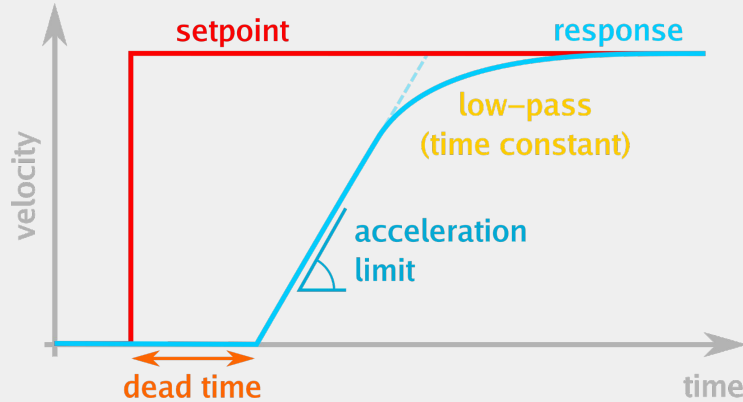
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“Cover key dynamics”

- **dead time**
finite transmission velocity

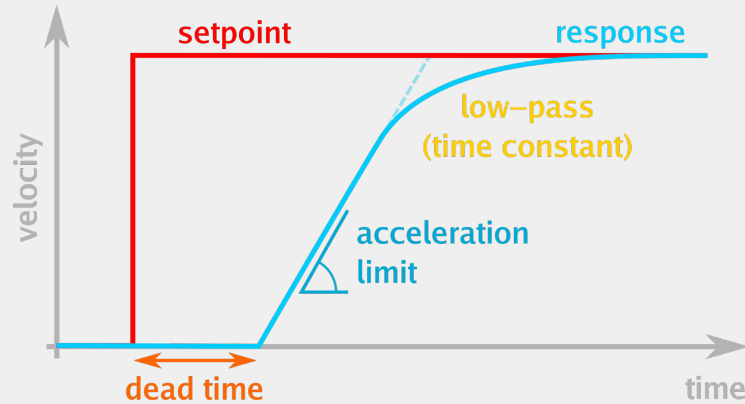
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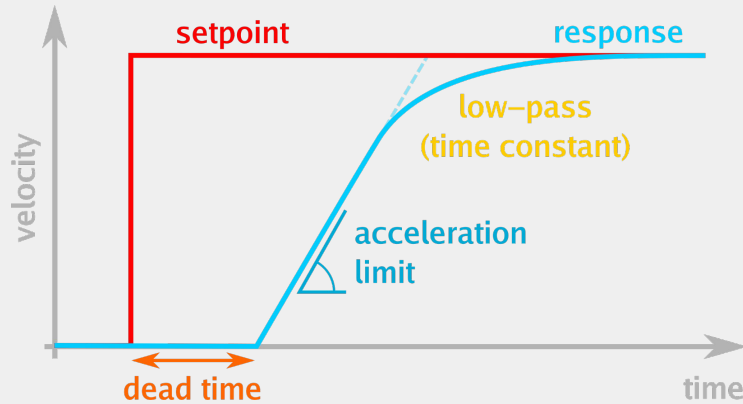
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- **low-pass time constant**
proportional control

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How to measure **dead time** etc.?

1. Apply step **reference**
2. Measure **response**
3. Read params from graph

Nav2 demo video

vehicle_dynamics_sim

! thanks !

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